

Version No: 20130715



Thank you for buying Agile products. Please read this manual carefully before assembling. We recommend that you keep this manual for future reference regarding tuning and maintenance.

#### SAFETY PRECAUTIONS

This radio controlled helicopter is NOT A TOY! It has some technical requirements, you must pay attention to the flying environment and correct operation. Never fly your radio controlled helicopter over people or near crowds. Teenagers must fly under the guardian's guide. Beginners must fly under the guardian of experienced pilot.

## **Product Specifications**

Length: 1370mm Height: 420mm Width: 200mm

Main Rotor Diameter: Ø1560 Main Blade Length: 690-713mm Tail Rotor Diameter: Ø294mm Tail Blade Length: 105-115mm

Motor Pinion: 19T Motor KV: 540KV

Driving Gear: (19/54)(20/66) Gear Ratio: 19T(9.37:1) Tail Gear Ratio: 4.75:1 Weight(w/o power): 4000g

Flying Weight: 5600g

Battery: 22.2V 5000mAh x2

ESC: 160-200A

Version No: 20130715

# 1.INTRODUCTION

Congratulations on your purchase of the Agile 7.2 radio controlled helicopter kit. Agile 7.2 was designed in Europe by Eng. Gaziano Roberto and is proudly manufactured by KDS Model. Our goal was to offer you something different with a minimum of parts, easy maintenance, and outstanding flying performances.

It's time to fly different!...

Enjoy the built and have a great time with you Agile 7.2!

#### **IMPORTANT NOTES**

R/C helicopters, including the AGILE 7.2 are not toys. R/C helicopters utilize various high-tech products and technologies to provide superior performance. Improper use of this product can result in serious injury or even death. Please read this manual carefully before using and make sure to be conscious of your own personal safety and the safety of others and your environment when operating all AGILE products. Agile 7.2, KDS Model, their affiliates and authorized distributors are not responsible for personal injuries to the operators and others, and property damages that could occur from the assembly, maintenance or your use/misuse of this product. Always respect the rules provided by your local remote control aircraft organization.

#### **NOTE FOR ASSEMBLY**

The following manual provide important instructions to correctly assemble the model. It is structured in a logical way, based on the work done in previous step. If you change the order, it may result in additional or unnecessary steps. So we suggest you to read this user manual very carefully to understand correctly the assembly procedure. Failure to do so may not only downgrade performances but also increase the risk of danger. Apply thread lock as indicated, allow the threadlock to cure before mounting parts. It is recommended to use threadlock on each bolt or screw that are engaged with metal parts.

# 2.SAFETY NOTES

#### • LOCATEAN APPROPRIATE LOCATION

R/C helicopters fly at high speed, thus posing a certain degree of potential danger. Choose an appropriate flying site consisting of flat, smooth ground, a clear open field, or a large open room, such as gymnasium or warehouse without obstacles. Do not fly near buildings, high voltage cables, or trees to ensure the safety of yourself, others and your model. Do not play your model in inclement weather, such as rain, wind, snow or darkness.



# • OBTAIN THE ASSISTANCE OF AN EXPERIENCED PILOT

Before turning on your model and transmitter, check to make sure no one else is operating on the same frequency. Frequency interference can cause your model, or other models to crash. The guidance provided by an experienced pilot will be invaluable for the assembly, tuning, trimming, and actual first flight(recommend you to practice with computer-based flight simulator).



#### • ALWAYS BE AWARE OF THE ROTATING BLADES

During the operation of the helicopter, the main rotor will be spinning at a high rate of speed. The blades are capable of inflicting serious bodily injury and damage the environment. Be conscious of your actions, and careful to keep your face, eyes, hands, and loose clothing away from the blades. Always fly the model a safe distance from yourself and others, as well as surrounding objects. Never take your eyes off the model or leave it unattended while it is turned on. Immediately turn off the model and transmitter when you have landed the model.



#### • PREVENT MOISTURE

R/C models are composed of many precision electrical components. It is critical to keep the model and associated equipment away from moisture and other contaminants. The introduction or exposure to water or moistrue in any form can cause the model to malfunction resulting in loss of use, or a crash. Do not operate or expose to rain or moisture.



#### • KEEP AWAY FROM HEAT

R/C models are made up of various forms of plastic. Plastic is very susceptible to damage or deformation due to extreme heat and cold climate. Make sure not to store the model near any source of heat such as an oven, or heater. It is best to store the model indoors, in a climate-controlled, room temperature environment.





#### PROPER OPERATION

Please use the replacement of parts on the manual to ensure the safety of instructors. This product is for R/C model, so do not use for other purpose.



#### SAFE OPERATION

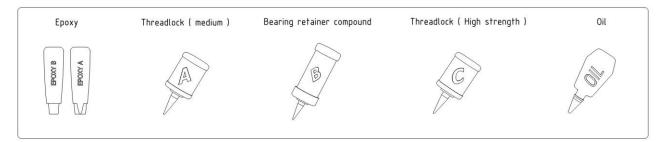
Operate this unit within your ability. Do not fly under tired condition or improper operation, which may cause danger.

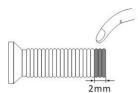


# 3.Tools Required

- -Hex drivers: 1.5, 2, 2.5, 3, 4mm
- -Nut Drivers: 2, 4, 7mm
- -Ball link pliers
- -Diagonal cutting pliers
- -Scissors
- -Metric ruler
- -Soldering iron + solder (for motor and ESC wiring)
- -Pitch gauge (for set up)
- -Swashplate leveller
- -Threadlock blue \* (medium)
- -Threadlock red \* (high strength)
- -Bearing retainer compound
- -Epoxy A+B Glue
- -Grease
- -Oil
- \*Colors may vary depending on your area.

# When you see the marks as below, please use glue or grease to ensure flying safety.





"A" Glue width: approx. 2mm

"OIL" Lubrication grease. "A" thread lock, apply a small amount on screws or metal parts and wipe surplus off. When disassembling, recommend to heat the metal joint about 15 seconds. (NOTE: Keep plastic parts away from heat.)



# RADIO TRANSMITTER AND ELECTRONIC EQUIPMENT REQUIRED FOR ASSEMBLY







Receiver(6-Channel or more)

or



Remote receiver

#### Transmitter

(7-Channel or more, helicopter system)

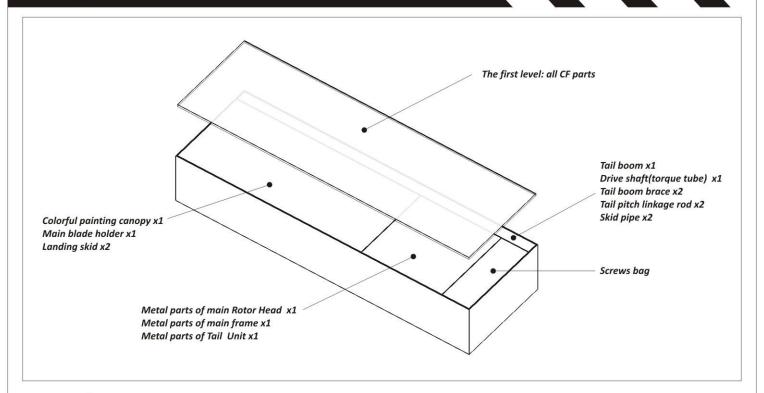
- \*Brushless electric motor: 12s 500\*550KV / 3000W (4mm Bolt holes, 30mm mount width, 6mm \* 37 motor shaft)
- Speed controller: minimum 120A (ESC specs limits should be rated accordingly to the maximum amps handling by the motor)
- •Lipo Batteries: 12s 4000-5500 mAh
- Electronic flybarless system
- •3 cyclic servos, standard size
- •1 tail rotor servo, high speed required
- •690~720 mm main rotor blades
- •105~115 mm tail rotor blades
- •6 channel or more helicopter transmitter system, 2.4 Ghz frequency preferred
- Receiver 6 channel or more (working with your transmitter specs)



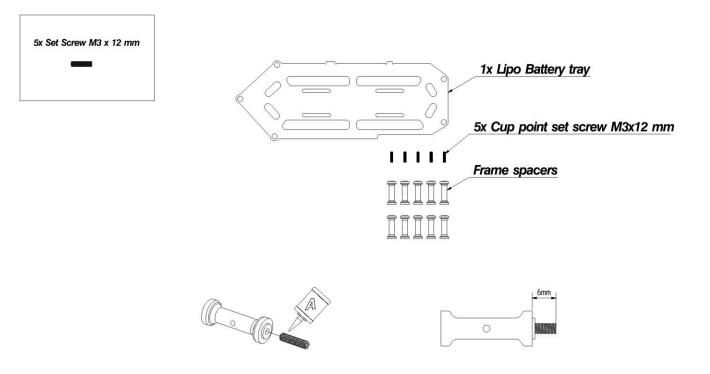
#### ADDITIONAL EQUIPMENT REQUIRED (not included)

- •Brushless electric motor: 12s Lipo 500~550KV / 3000W
- (4mm Bolt holes, 30mm mount width, 6mm \* 37mm motor shaft)
- •Speed controller: minimum 120A
- (ESC specs limits should be rated accordingly to the maximum amps handling by the motor)
- •Lipo Batteries: 12s 4000-5500 mAh
- Electronic flybarless system
- •3 cyclic servos, standard size
- •1 tail rotor servo, standard size, high speed required
- •690~720 mm main rotor blades
- •105~115 mm tail rotor blades
- •6 channel or more helicopter transmitter system, 2.4 Ghz frequency preferred
- $\bullet \textbf{Receiver 6 channel or more (working with your transmitter specs)} \\$

# 5.Package Illustration

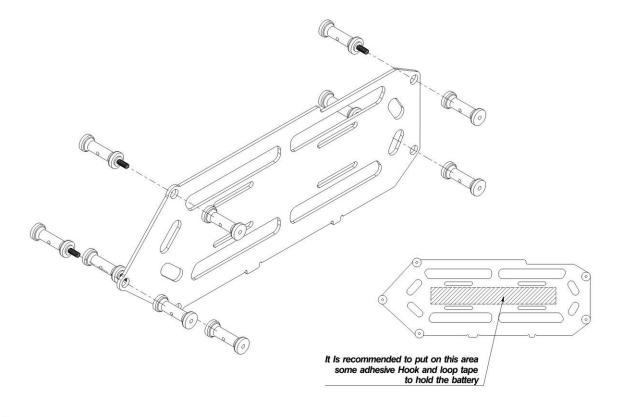




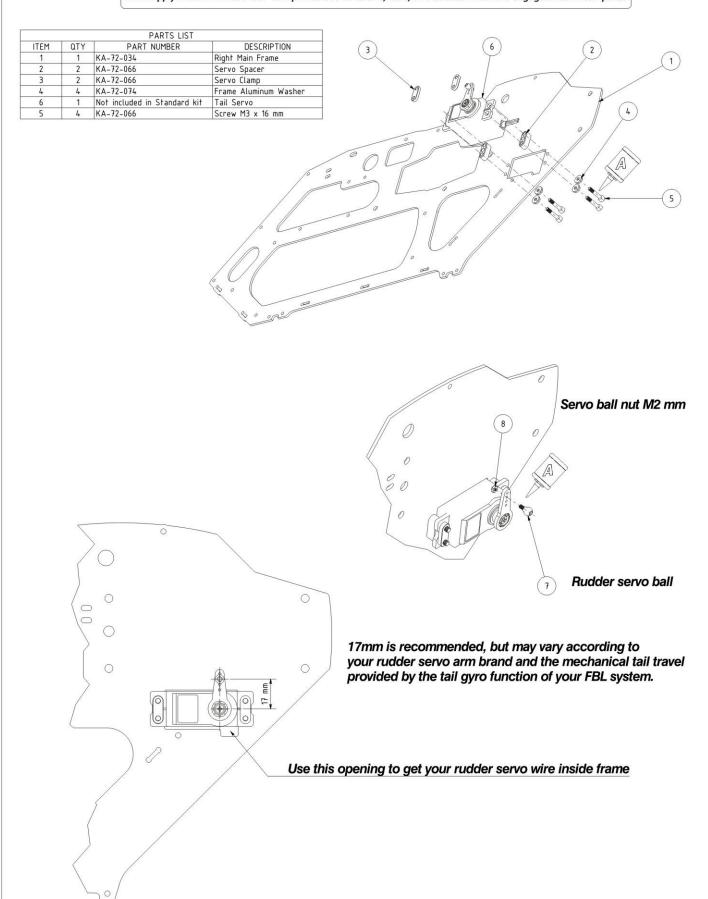


You may use some pins thoughout this drilling to hold frame spacer when tightening screw.

Attention: Be sure that frame spacers are correctly mounted, housing sholder must be placed into carbon battery tray Do not overtighten

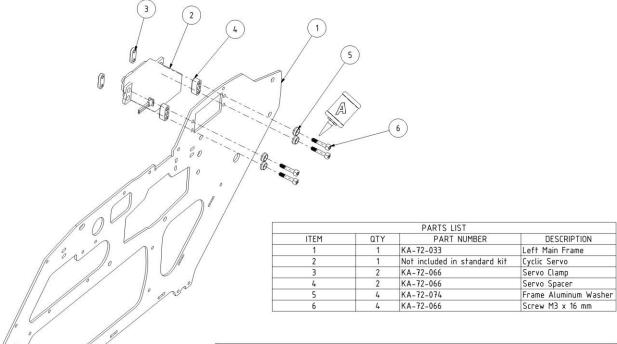


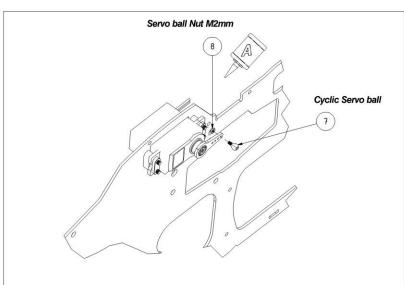


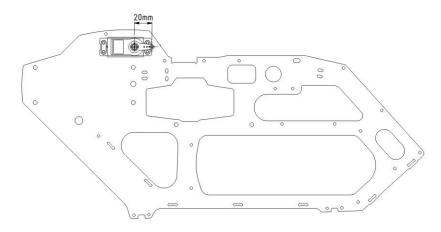




REM: Apply Medium Thread lock or Equivalent to all screws, balls, and threads which are engaged with metal-parts.





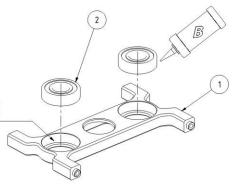


20 mm is recommended, length may vary according to your cyclic servo arm brand, and the mechanical cyclic/pitch travel provided by your FBL system settings



		PARTS LIST	201
ITEM	QTY	PART NUMBER	DESCRIPTION
1	1	KA-72-011	MAIN SHAFT BEARING
			BLOCK
2	2	KA- 72-089	BEARING 10 x 22 x 6

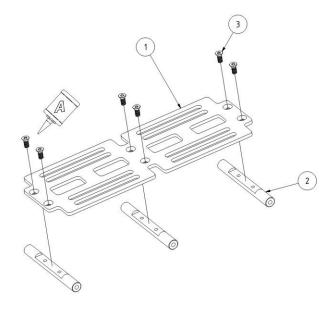
Clean surface with alcohol. Apply Loctite Retaining Compound to this area wait 24H at least before flying



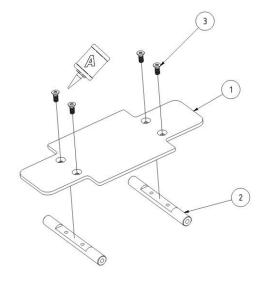
Important:

Keep this orientation in mind for future assembly Bearings must facing up

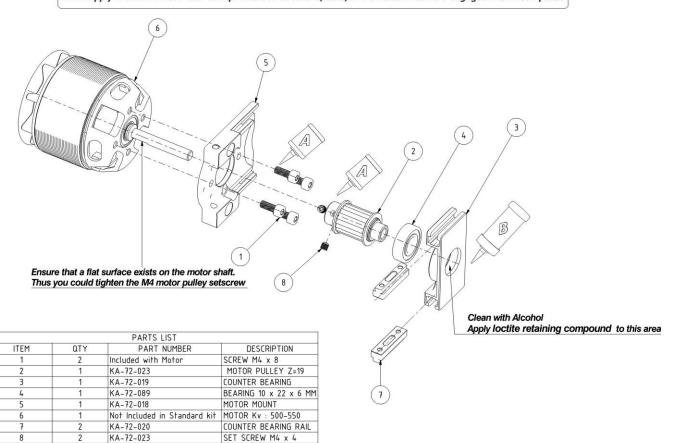
		PARTS LIST	
ITEM	QTY	PART NUMBER	DESCRIPTION
1	1	KA-72-035	ESC FRAME
2	3	KA-72-060	SPACER
3	6	KA-72-077	Flat Head Screw M2.5 x 6 mm

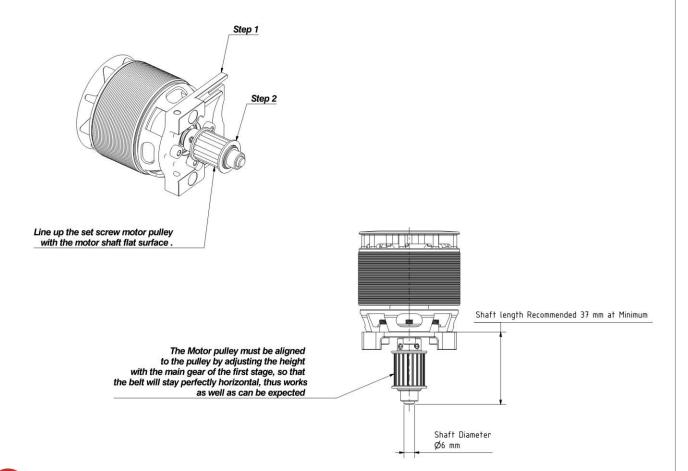


		PARTS LIST	
ITEM	QTY	PART NUMBER	DESCRIPTION
1	1	KA-72-039	GYRO MOUNT
2	2	KA-72-060	SPACER
3	4	KA-72-077	Flat Head Screw M25 x 6 mm

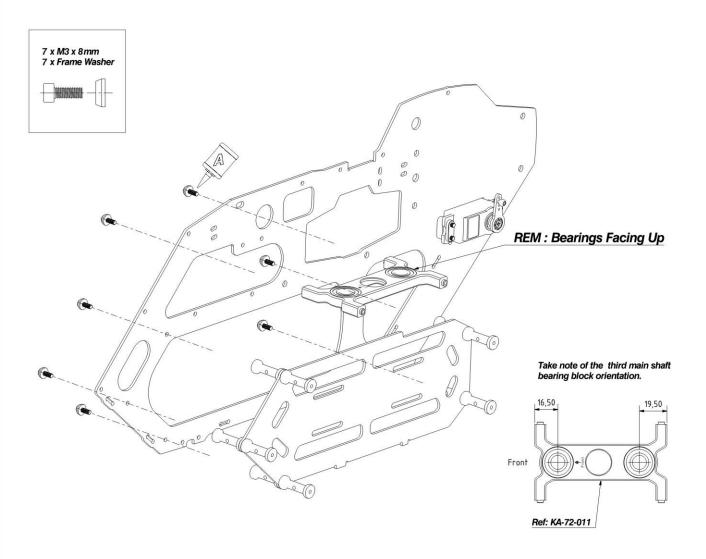


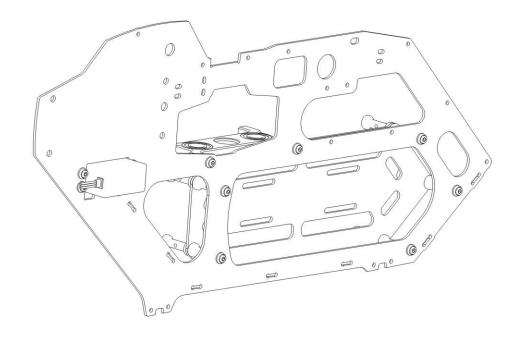




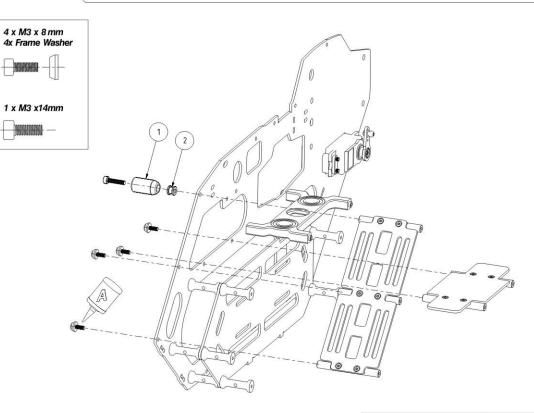




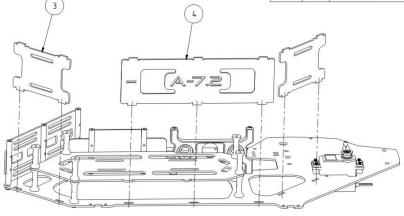


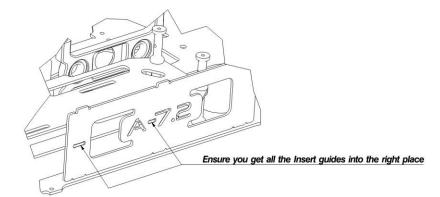




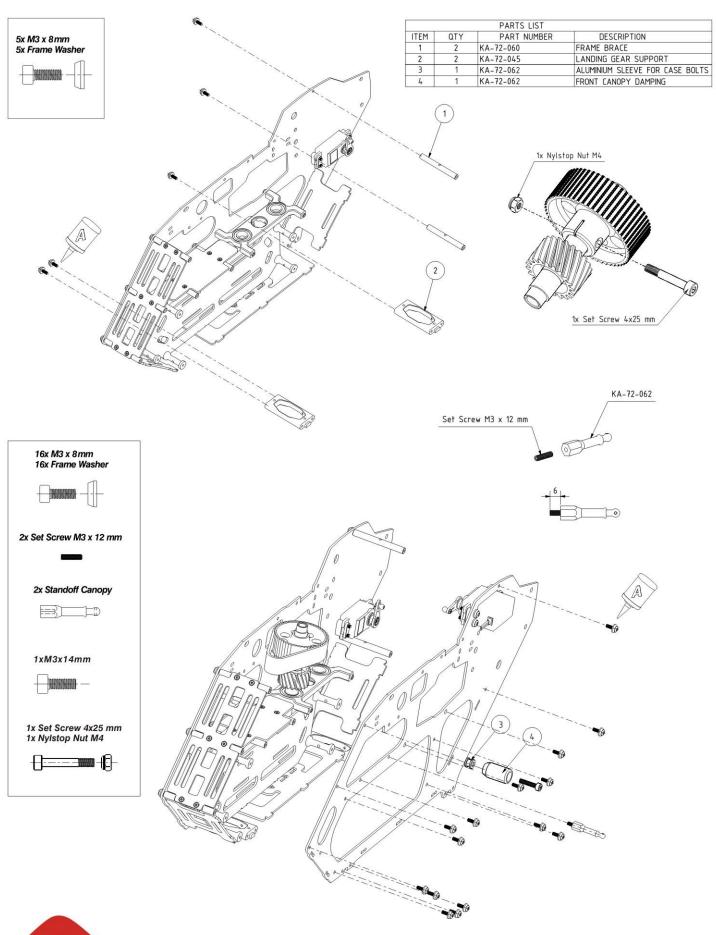


		PARTS LIST	
ITEM	QTY	PART NUMBER	DESCRIPTION
1	1	KA-72-062	FRONT CANOPY DAMPING
2	1	KA-72-062	ALUMINIUM SLEEVE FOR CASE BOLTS
3	1	KA-72-038	ELECTRONIC BOARD
4	1	KA-72-037	BOTTOM PLATE

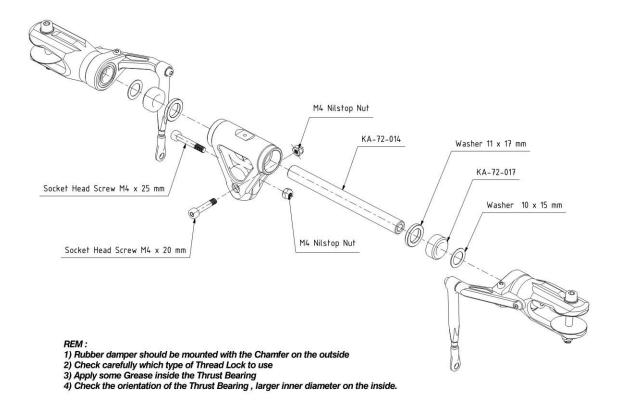


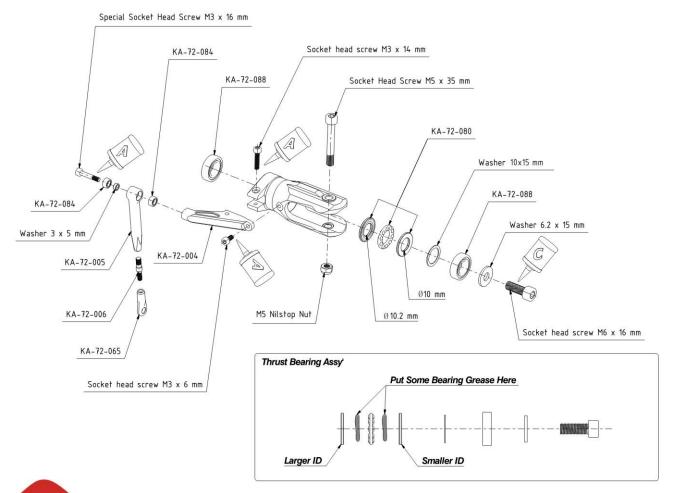




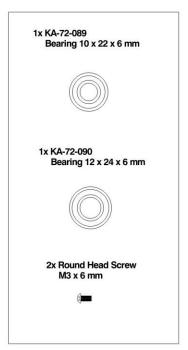


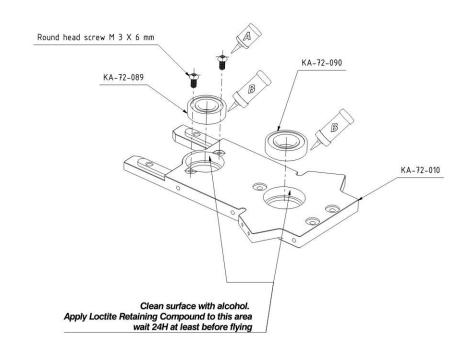


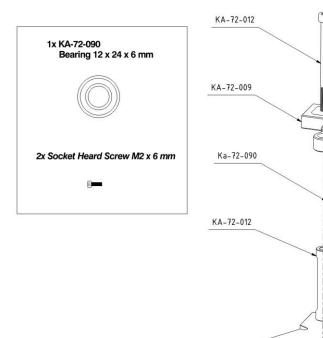


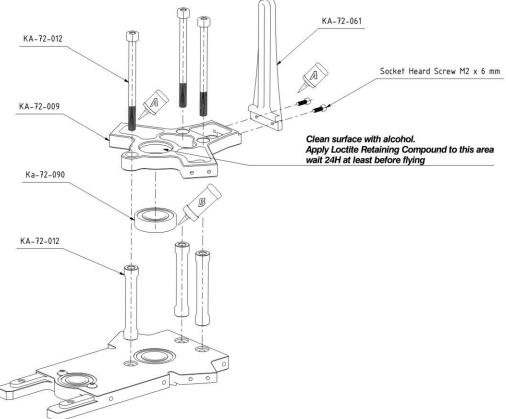




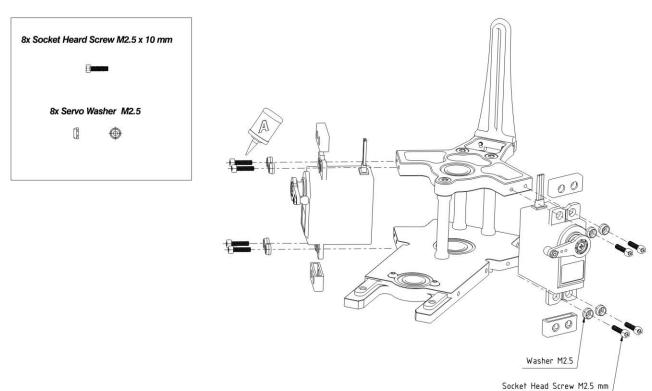




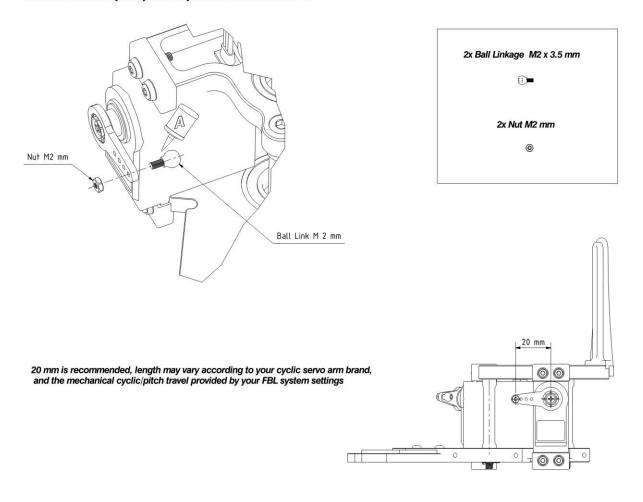




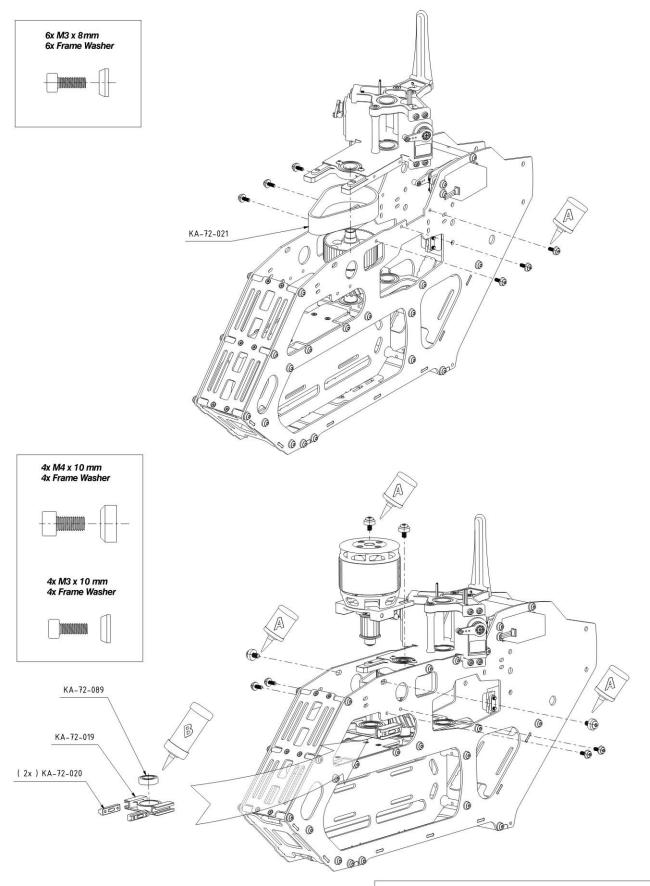


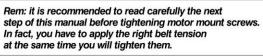


REM: Before mounting servo arms, do not forget to set their neutral position. Check the manual of your flybarless system for more informations.

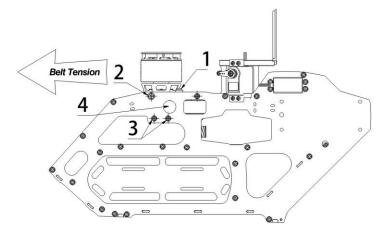






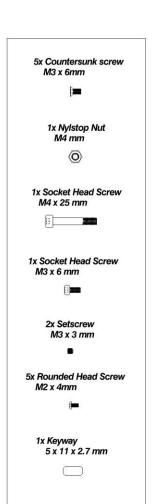


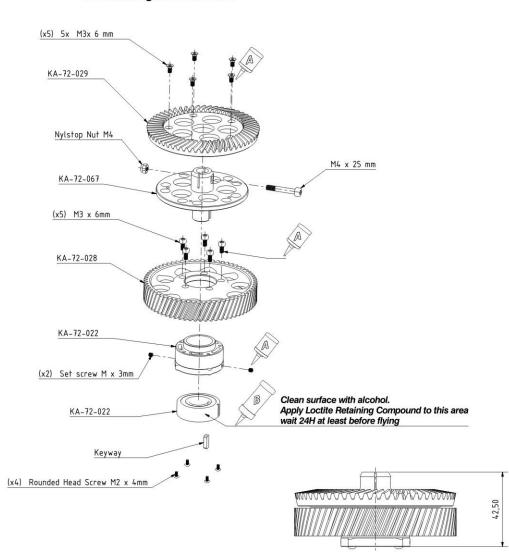




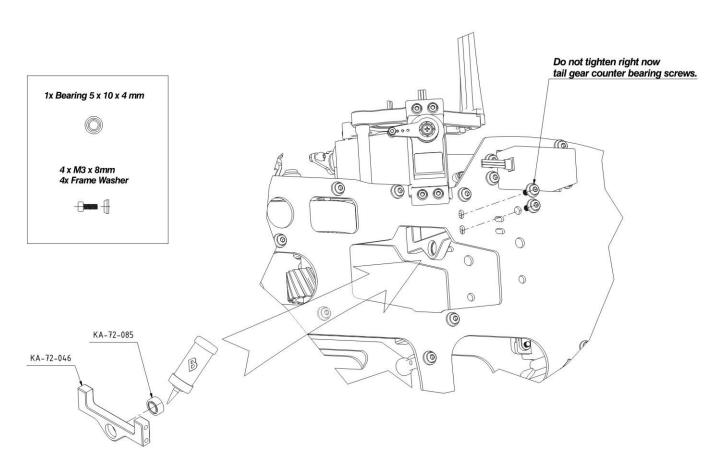
- 1. Push the motor in the opposite direction of the main shaft as far as you can (by hand).
- 2. Tighten slide screws # 1
- 3. Tighten motor mount locking screws #2
  4. Rotate the motor several times by hand. Ensure that belt is correctly aligned with the big pulley.
- 5. Tighten counter bearing screws #3
- 6. You can check the belt tension by hand, you just have to push the belt with one of your finger through the round opening on frame # 4. It should be difficult to push motor belt.

# Assembling the Main Gear



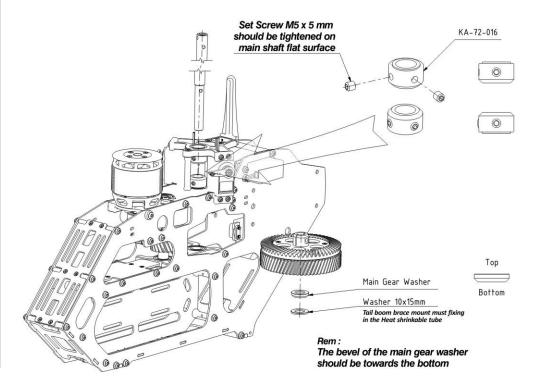




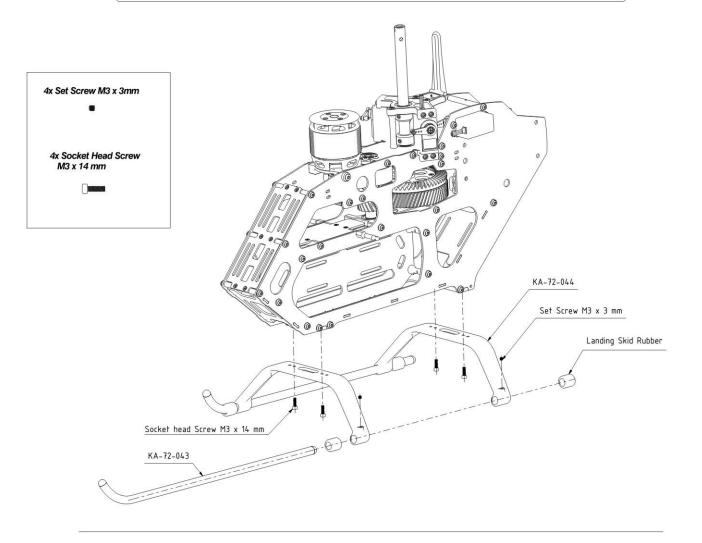


Rem: the main shaft should slide along the 3 bearing blocks (upper, medium and lower) effortless. If not the case, remove the 6 screws of the medium bearing block, then slide down the main shaft and tighten again theses 6 screws.

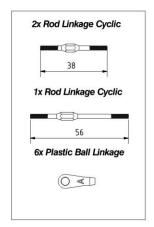


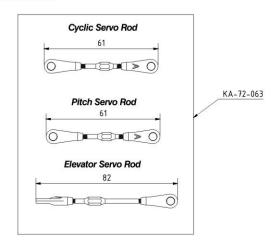


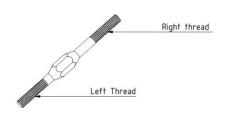




# Cyclic linkage installation

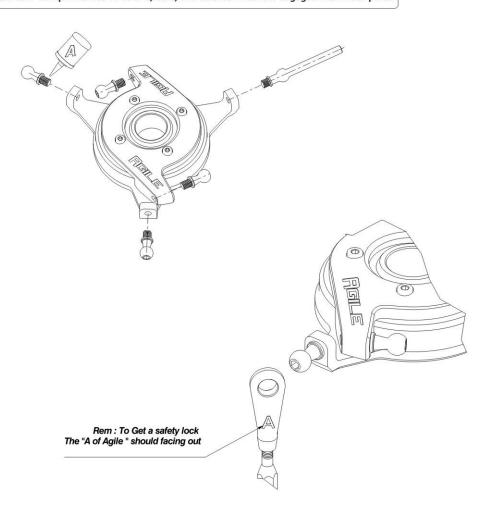




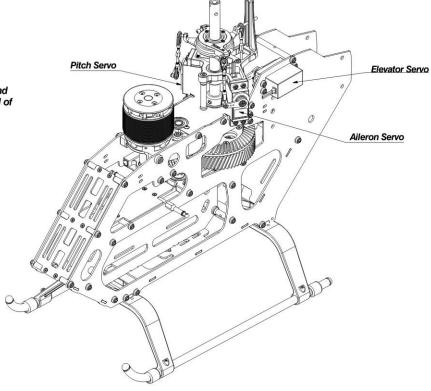








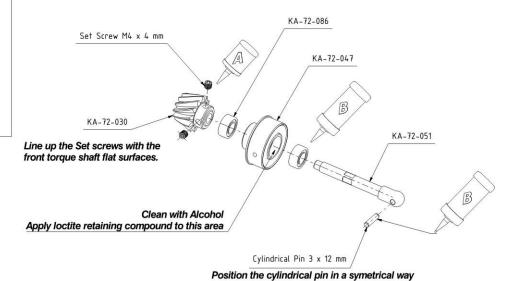
Rem: At this point, you may set the neutral position of your servos and swatchplate according to the manual of your FLB system.

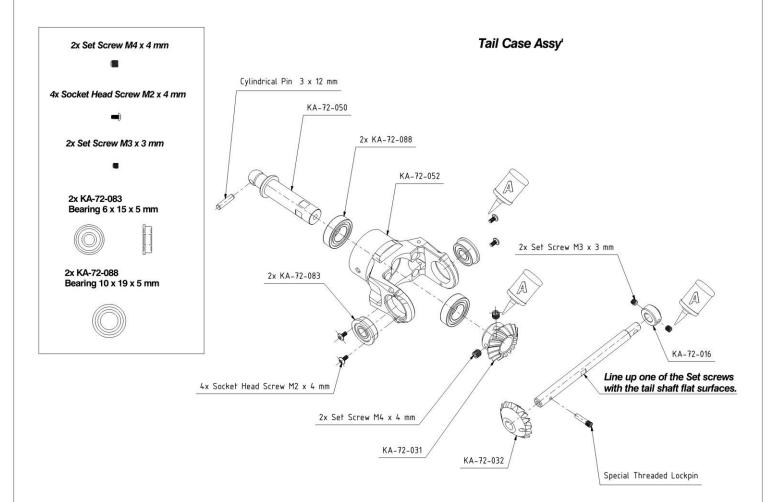


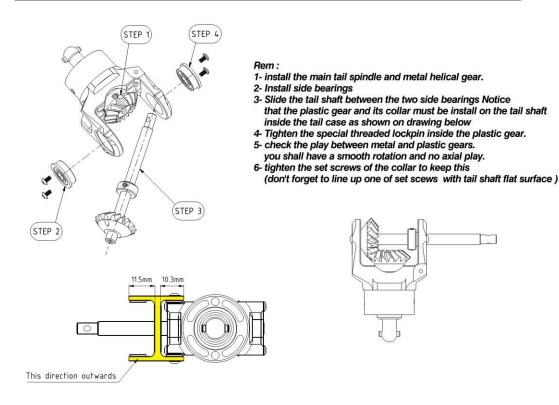


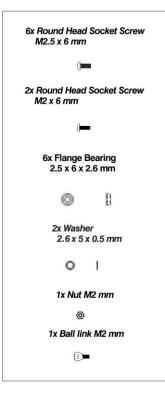
# 2x Bearing 6 x 13 x 5 mm 1x Set Screw M 4 x 4 mm 1x Pin Dia: 3 x 12 mm

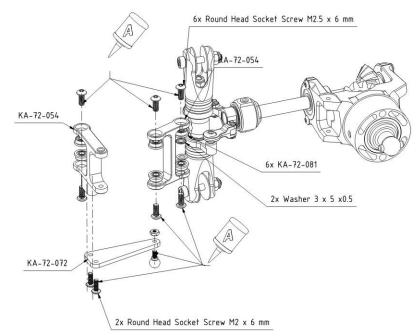
# Front Torque tube Assy

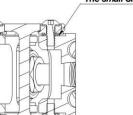








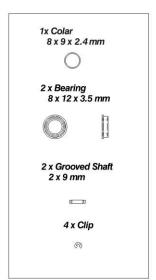


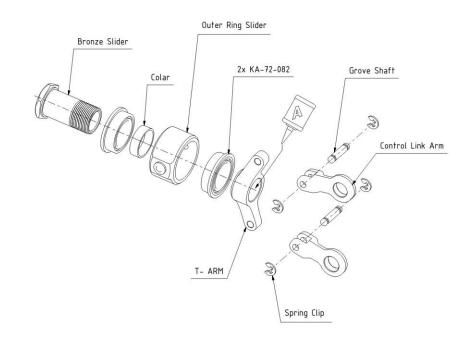


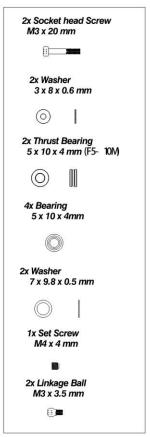
riem: Take care of the Washer Orientation The small Shoulder diameter must face the bearing



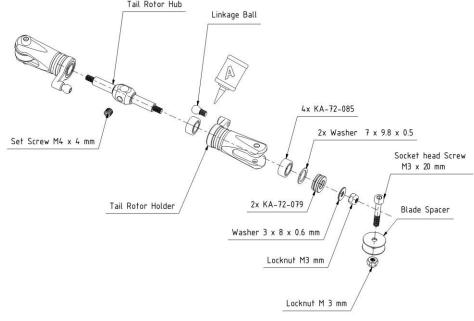
## Pre Assembled Tail Slider Mechanism

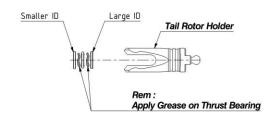




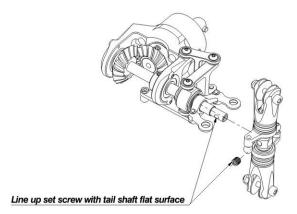


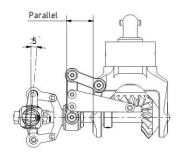
# Pre Assembled Tail Blade grip Tail Rotor Hub Linkage Ball



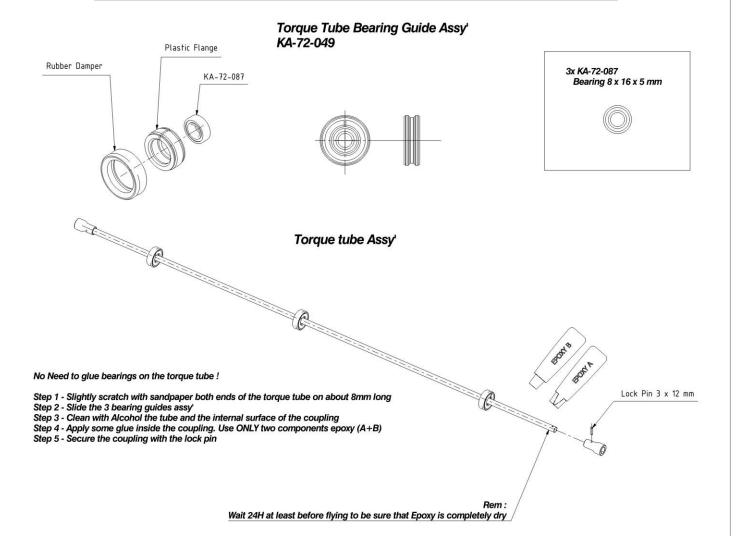




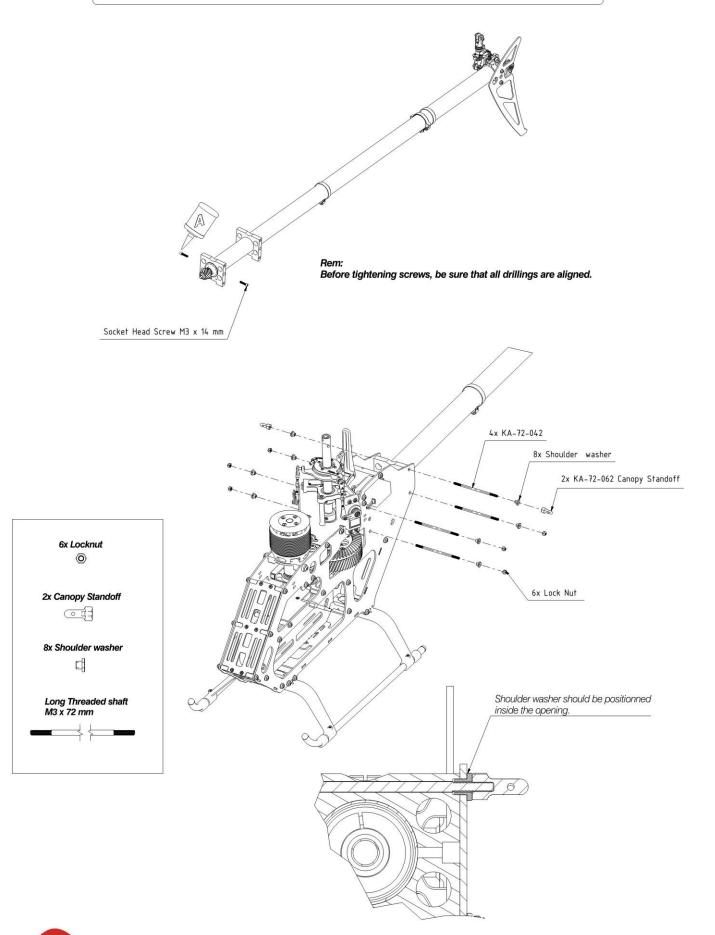




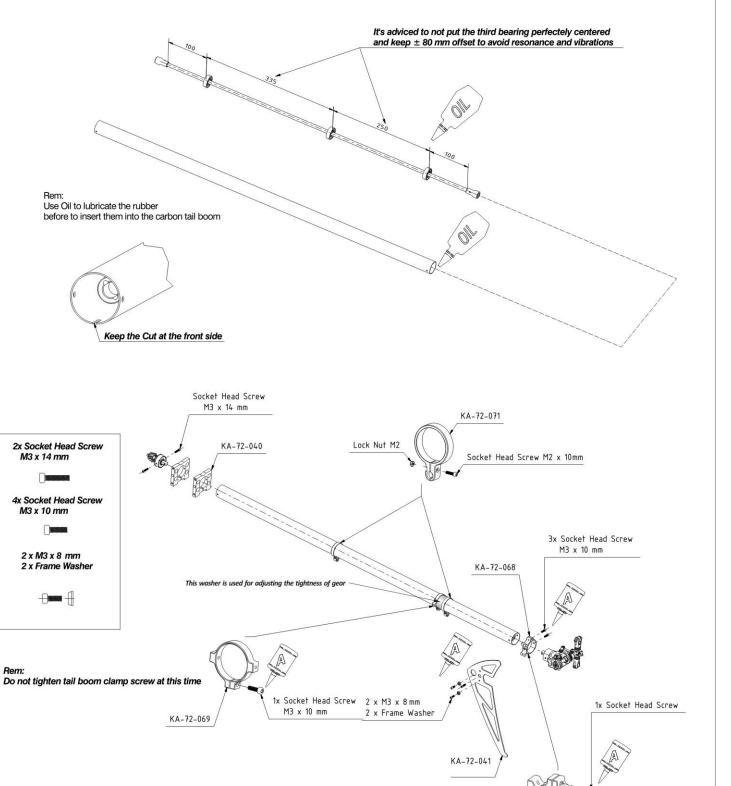
Rem: At the Neutral position to get the best resolution  $\pm 5^{\circ}$  of Pitch Nevertheless you may take into account your FBL system recommendations .











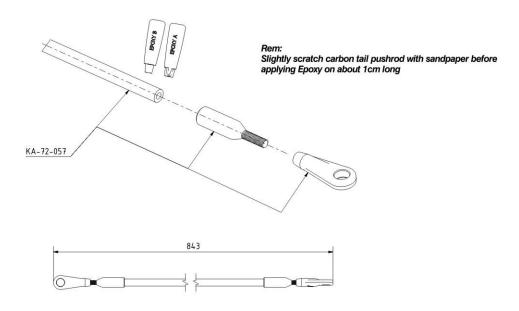


1654

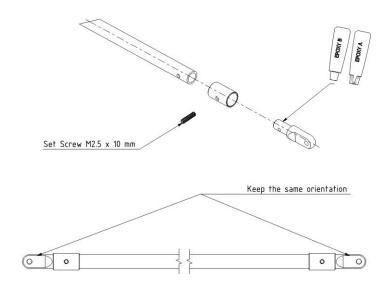
∄28

Tail Boom Clamp

KA-72-068

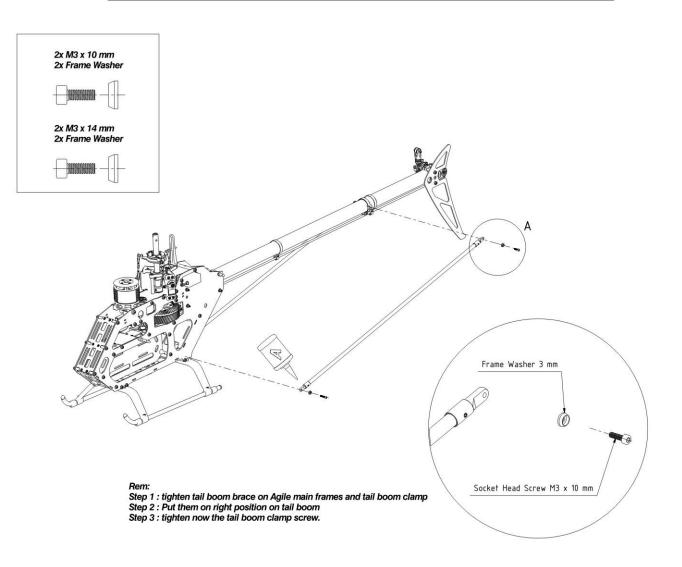


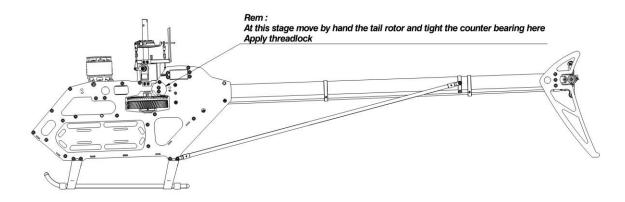
# Tail Boom Brace Assy



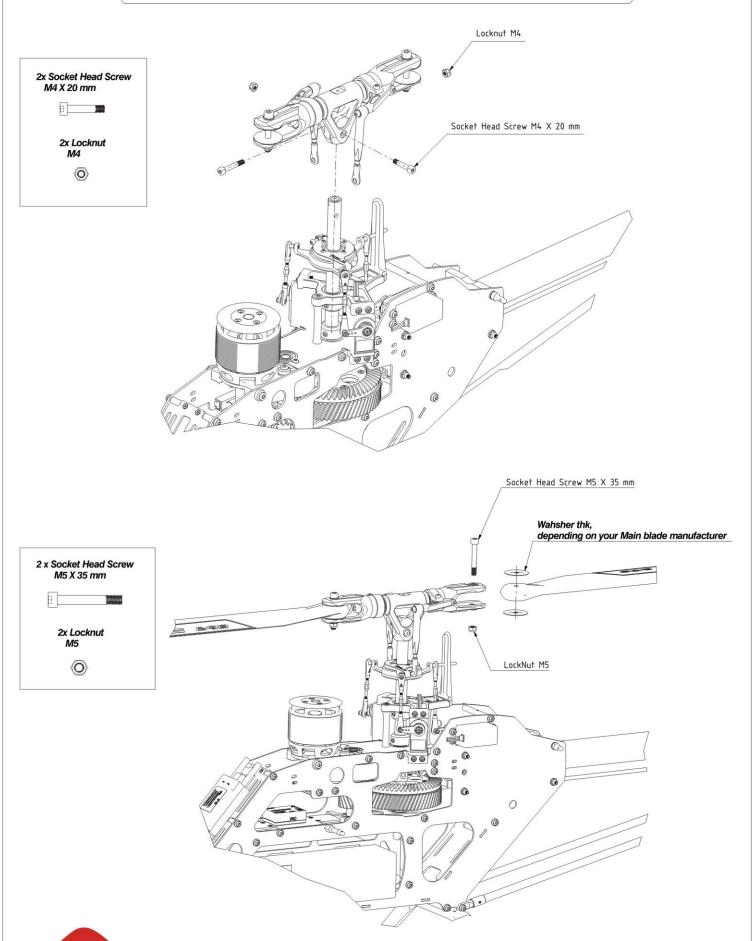
The best solution to mount tail boom brace correctly is to apply some Epoxy as shown. Then, screw them on position on Agile main frames and tail boom clamp. Insert set screws to secure. And let Epoxy drying for at least 24H.

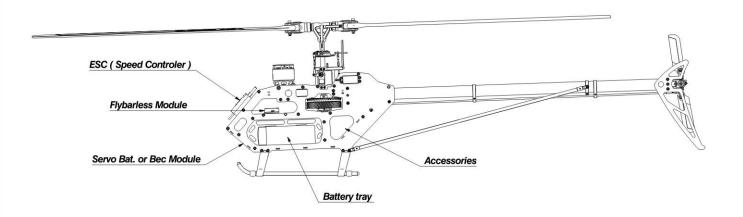


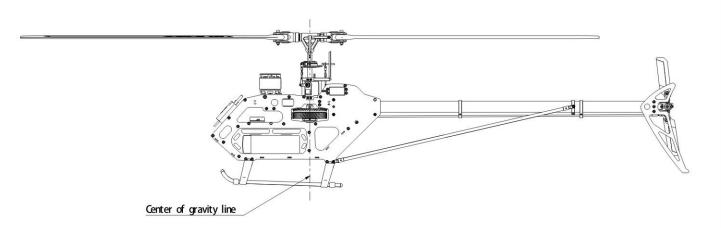












Important Before fly,

- 1) check the servo direction , according your flybarless module.
- 2) make sure your helicopter is well balanced in term of center of gravity passing thrue the main shaft .

# Calculation for your total ratio:

Pignon z=17 (54/17) x ( 66 / 20 ) = 10.48

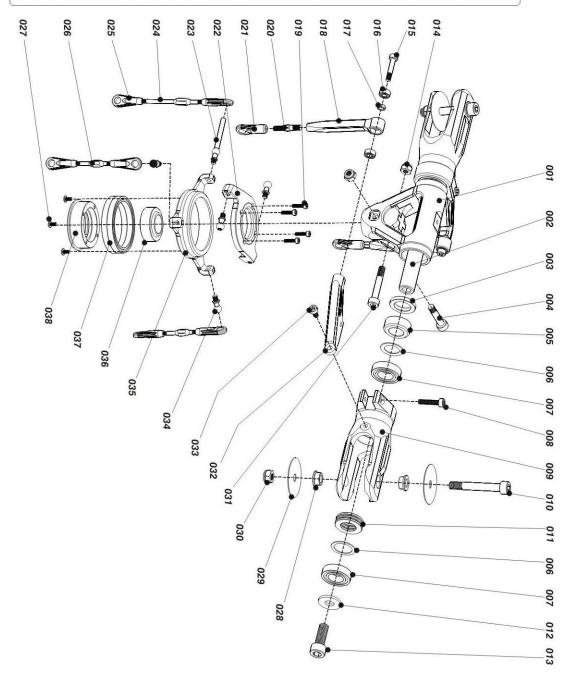
Pignon z=18 (54/20) x ( 66 / 20 ) =9.9

Pignon z=19 (54/19) x ( 66 / 20 ) = 9.378

Pignon z=20 (54/20) x ( 66 / 20 ) = 8.91



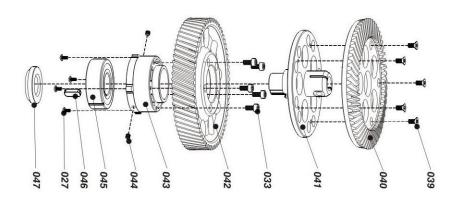
REM: Apply Medium Thread lock or Equivalent to all screws, balls, and threads which are engaged with metal-parts.



Dearing ( 400 401 4)	VA-12-001	
	700 CT AV	037
Oscillating bearing	KA-72-007	036
Swashplate Outer ring	KA-72-007	035
Linkage ball A	KA-72-007	034
Hex socket cap screw (M3×6)	KA-72-004	033
Main rotor branch control	KA-72-004	032
Hex socket cap screw (M4*25)	KA-72-003	031
M5 NUT	KA-72-002	030
Washer ( ♦ 5. 2* ♦ 26*0. 5)	KA-72-002	029
Screw socket	KA-72-002	028
Button head socket cap	KA-72-007	027
Linkage rod (38mm)	KA-72-063	026
Ball link B	KA-72-063	025
Linkage rod (56mm)	KA-72-063	024
Swashplate mounting pin	KA-72-007	023
Swashplate Inner upper part	KA-72-007	022
Linkage ball A	KA-72-005	021
Bolt	KA-72-005	020
Hex socket cap screw (M2*8)	KA-72-007	019
Draw arm	KA-72-005	018
Collar ( + 3* + 5*2.1)	KA-72-005	017
Bearing ( + 3* + 7*3)	KA-72-005	016
Hex socket cap screw (M3*1	KA-72-005	015
M4 NUT	KA-72-003	014
Hex socket cap screw (M6*1	KA-72-014	013
Washer ( $\phi$ 6. 2* $\phi$ 15*1. 5)	KA-72-014	012
Thrust bearing (F10-18M)	KA-72-002	011
Hex socket cap screw (M5×35)	KA-72-002	010
Plastic main rotor holder	KA-72-002	009
Hex socket cap screw (M3*14)	KA-72-004	800
Bearing ( \$ 10* \$ 19*5)	KA-72-002	007
Washer ( ф 10. 2* ф 15*0.	KA-72-003	900
Damper rubber ( ♦ 9.8* ♦ 17*7)	KA-72-003	005
Hex socket cap screw (M4*20)	KA-72-003	004
Washer ( ⊕ 11* ⊕ 17*2.5)	KA-72-014	003
Feathering shaft	KA-72-014	002
Main rotor hosing	KA-72-003	001
Description	ran ivo.	NO.

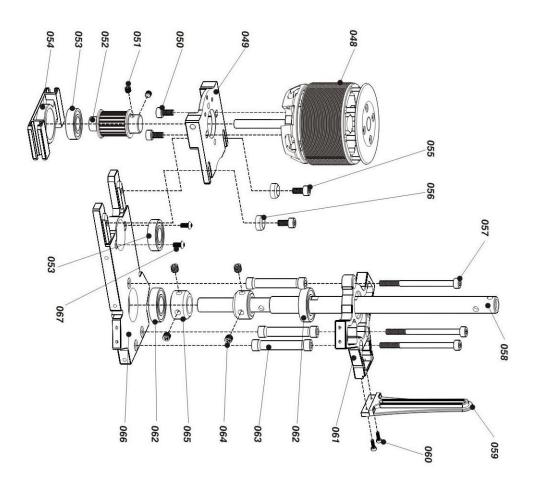


	Washer ( ф 10* ф 20*4)	KA-72-076	047
	Flat pin	KA-72-067	046
	One way clutch	KA-72-022	045
	KIMI screw (M3*3)	KA-72-022	044
	One way clutch mountr	KA-72-022	043
	60T Main gear	KA-72-028	042
	Gear hub	KA-72-067	041
_	57T Spiral bevel gear	KA-72-029	040
	Flat socket head cap (M3*6)	KA-72-067	039
Quantity	Description	Part No.	No.

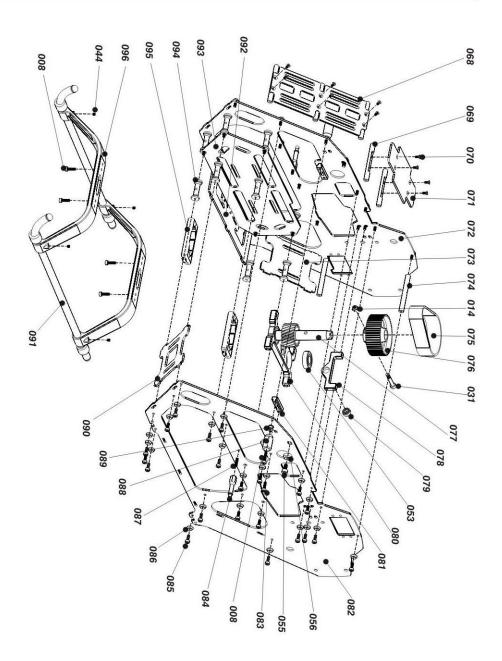


057	056	055	054	053	052	051	050	049	048
KA-72-012	KA-72-010	KA-72-010	KA-72-019	KA-72-019	KA-72-025	KA-72-025	KA-72-018	KA-72-018	KA-72-092
Hex socket cap screw (M4*55)	Aluminum washer	Hex socket cap screw (M4*10)	Under motor block	Bearing ( \$ 10* \$ 22*6)	19T Main pinion gear	KIMI screw ( M4*4)	Hex socket cap screw (M4*8)	Moto mountr	Motor 500-540KV
ယ	4	4	1	4	1	7	2	1	1

067 KA-7	066 KA-7	065 KA-7	064 KA-7	063 KA-7	062 KA-7	061 KA-7	060 KA-7	059 KA-7	058 KA-
KA-72-010	KA-72-010	KA-72-016	KA-72-016	KA-72-012	KA-72-009	KA-72-009	KA-72-061	KA-72-061	KA-72-013
Button head socket cap (M3*4)	Main shaft middle bearing mount	Lock collar	KIMI screw (M5*5)	Main shaft bearing block pillar	Bearing ( \$ 12* \$ 24*6)	Main shaft upper bearing block mount	Hex socket cap screw (M2*6)	Swashplate Anti-rotation bracket	Main shaft
2	1	2	4	ယ	2	1	2	1	7







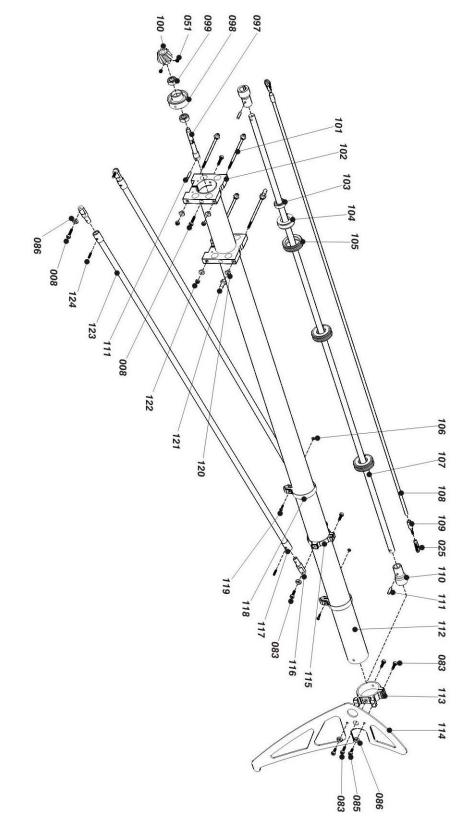
KA-72-044 Landing skid	KA-72-045 Landing skid mount	KA-72-060 Frame spacers	KA-72-036 Lipo battery tray	KA-72-037 Bottom plate	KA-72-043 Skid pipe	KA-72-038 CF front elec	KA-72-062 Aluminum sleeve for	KA-72-062 Canopy spacer	KA-72-062 KIMI screw (M3*12)	KA-72-074 Conical washers	KA-72-077 Hex socket cap screw	KA-72-062 Front canopy	KA-72-020 Hex socket of	KA-72-033 Main frame L	KA-72-020 Motor block sliding rail	KA-72-011 Main shaft under I	KA-72-046 Bearing ( \$5* \$10*4)	KA-72-046 Front drive shaft mount	KA-72-027 Second reduction gear	KA-72-026 First reduction gear 54T	KA-72-021 3M-213 Sync	KA-72-060 Frame columns(spacers)	KA-72-038 CF back-end	KA-72-034 Main frame R	KA-72-039 CF middle el	KA-72-060 Sink hexangular screw	KA-72-060 Frame connecting bolt	KA-72-035 Swashplate	Description
	mount	NS.	tray			CF front electronics board	eeve for case bolts	er	/M3*12)	hers	ap screw (M3*8)	Front canopy mounting bolt	Hex socket cap screw (M3*10)		sliding rail	Main shaft under bearing block(botton plate)	* \phi 10*4)	haft mount	ction gear	n gear 54T	Synchronous belt	ıns(spacers)	CF back-end electronics board	3	CF middle electronic board	ular screw	ecting bolt		
0	2	10	1	1	2	1	2	2	7	48	46	2	4	1	2	1	5	1	1	1	1	2	1	1	1	10	Si Si	1	Quantity



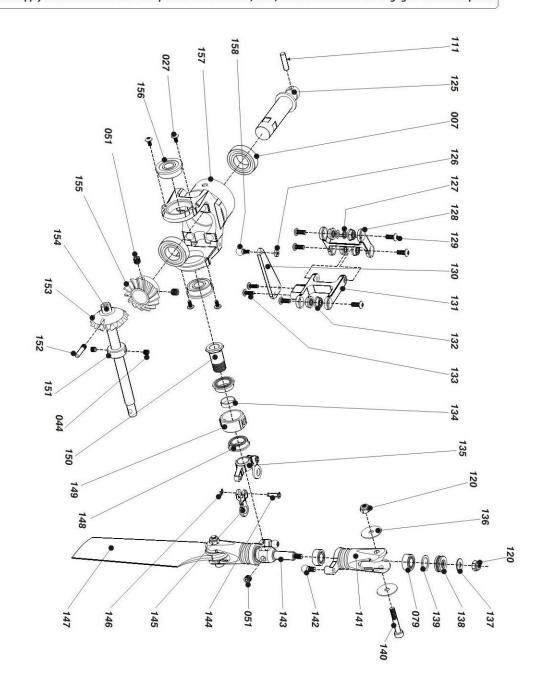
	Rubber damper	KA-72-049	105
- 3	Tail drive bearing mount	KA-72-049	104
	Bearing ( \$ 8* \$ 16*5)	KA-72-049	103
	Tail boom mount	KA-72-040	102
	Doubled-headed screw rod	KA-72-042	101
	Helical bevel gear 12Z	K4-72-030	100
	Bearing ( 4 6* 4 13*5)	KA-72-047	099
	Middle drive shaft mount	KA-72-047	860
	Front universal joint drive shaft	KA-72-051	097
Quantity	Description	Part No.	No.

115	114	113	112	111	110	109	108	107	106
KA-72-069	KA-72-041	KA-72-068	KA-72-070	KA-72-048	KA-72-048	KA-72-058	KA-72-048	KA-72-048	KA-72-071
Tail boom brace mount	CF vertical stabilizer	Vertical stabilizer mount	Tail boom	Pin ( + 3*12)	Drive shaft joint	Push link connecting set	Tail linkage rod	Torque tube	M2 Nut
1	1	1	1	4	2	2	1	1	2

124 K	123 K	122 K	121 K	120 K	119 K	118 K	117 K	116 K
KA-72-057	KA-72-057	KA-72-042	KA-72-062	KA-72-042	KA-72-071	KA-72-071	KA-72-057	KA-72-057
KIMI screw (M2.5*10)	Tail boom brace	M3 Nut	Behind canopy mounting bolt	Aluminum sleeve	Hex socket cap screw (M2*10)	Hex socket cap screw	Aluminum sleeve	Tail boom brace end
4	2	10	2	00	2	2	4	4







		₹,	evel gear 15T		el gear 15T		collers ring		mount	*3.5)			der		holder			rew (M3*20)	0.6)	10M)	0.6)	*0.5)		→ 8* → 9*2. 5)	t screw (M2.5*6)	5*2.6)			t screw (M2.5*6)	unt	·		joint drive shaft
Tail gear box Short linkage ball	Tail gear box	Bearing ( + 6* + 15*5)	Back-end drive spiral bevel	Tail shaft	Tail shaft spiral bevel gear	Pin ( \$2.5*12)	Tail shaft locking co	Tail push bearing	Tail push bearing n	Bearing ( + 8* + 12*3	CF Tail blade	E-ring	Ball link for tail holder	Pin ( \$2*9)	Tail rotor T type ho	Slinkage ball B	Tail rotor holder	Hex socket cap screw	Washer ( ♦ 3* ♦ 8*0. 6)	Thrust bearing(F5-10M)	Washer ( + 3* + 8*0. 6)	Washer ( ♦ 3* ♦ 15*0.	T type arm	Aluminum sleeve ( \$ 8* \$ 9*2	Round head hex socket screw	Bearing ( $\phi$ 2.5* $\phi$	Tail rocket arm	Tail control arm	Round head hex socket screw	Tail rocker arm mount	Washer (	M2 NUT	Back-end universal joint drive
KA-72-072	KA-72-052	KA-72-052	KA-72-031	KA-72-015	KA-72-032	KA-72-032	KA-72-073	KA-72-053	KA-72-053	KA-72-053		KA-72-053	KA-72-053	KA-72-053	KA-72-055	KA-72-055	KA-72-055	KA-72-055	KA-72-055	KA-72-055	KA-72-055	KA-72-055	KA-72-053	KA-72-053	KA-72-072	KA-72-054	KA-72-054	KA-72-072	KA-72-054	KA-72-054	KA-72-076	KA-72-072	KA-72-050
158	157	156	155	154	153	152	151	150	149	148	147	146	145	144	143	142	141	140	139	138	137	136	135	134	133	132	131	130	129	128	127	126	125



# 37.PARTS LIST 1



- 2 x Main rotor holder
  4 x Rotor holder washer
  2 x Stainless steel gasket 010.2x015x0.5mm
  2 x Plane bearing 010x019x5mm
  2 x Thrust bearing 150-18M
  2 x Nylon lock nuts M4
  2 x Cup head socket head half tooth screw M5x35mm
  4 x Washers 05x0126x0.5mm
- 1 x Main rotor house

Main rotor house

KA-72-003

- 1 x Main rotor house
  2 x Stainless steel gasket 010.2x015x0.5mm
  2 x Nylon lock nuts M4
  2 x Feathering shaft rubber ring(dampers)
  2 x Aluminum gasket feathering shaft damper 011x17x2.5mm
  1 x Cup head socket head half tooth screw M4x25mm
  1 x Cup head socket head half tooth screw M4x25mm



Main rotor arm

KA-72-004

2 x Main rotor arm 2 x Cup head socket head half tooth screw M3x14mm 2 x Cup head socket head half tooth screw M3x6mm



- 2 x Connecting linkage 2 x Double-headed screw 2 x Cooper head (93x)5x2.1mm 2 x Cup head socket head half tooth screw M3x16mm 2 x Ball Linkage Rod 5.0 4 x Plane bearing (93x07x3mm



4 x Double-headed screw



- 1 x Swashplate nose pile 4 x Ball part Ø5.0x10.7mm 4 x Cup head socket head screw M2x8mm 2 x Umbrella head screws M2x4mm
- 2 x Oscillating bearing



1 x Swashplate outer ring



1 x Main shaft upper bearing block mount 4 x Cup head socket head screw M2.5x10mm 1 x Imported plane bearing  $\,$  012x24x6mm





1 x Under bearing block 2 x Imported plane bearing 012x024x6mm4 x Cup head socket head screw M3x8mm

Main shaft bearing block pillar KA-72-012





- 2 x Feathering Shaft 4 x Cup head socket head screw M6x16mm 4 x Stainless steel gasket  $\emptyset$ 6.2x $\emptyset$ 15x1.5mm



2 x Tail shaft



2 x Spacing ring collers 4 x Grub screw M4x4mm







1 x under motor block 1 x imported plane bearing @10x@22x6mm

1 x Motor gear 2 x Set screws M4X4mm



2 x motor block sliding rail 4 x cup head socket head screw M3x10mm

Motor pinion gear 19T



1 x synchronous belt 3M-213-18



Motor pinion gear 18T KA-72-024

KA-72-025 1 x Motor gear 2 x Set screws M4X4mm First reduction gear 54T KA-72-026 1 x First reduction gear 54T 1 x Cup head socket hear half tooth screws M4x25mm 1 x Nylon lock nuts M4





- 1 x Second reduction gear (20Z) 1 x Cup head socket head half tooth screws M4x25mm 1 x Nylon lock nuts M4



Front spiral bevel gear KA-72-029

1 x Front spiral bevel gear(57Z)





Back-end drive spiral bevel gear



2 x Grub screw M4x4mm 1 x Helical bevel gear (15Z)

Tail shaft spiral bevel gear KA-72-032

1 x Helical bevel gear (15Z) 1 x Tail shaft pin



1 x CF Right side plate (r/h side main frame)



1 x CF Left side plate (I/h side main frame)

CF Front electronic board KA-72-035



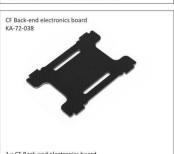
1 x CF Front electronic board



1 x CF Batteries spacing board



1 x CF Bottom plate



CF Middle electronic board KA-72-039



1 x CF middle electronic board



2 x Tail boom mount



1 x CF Vertical stabilizer



Aluminum landing hear pipe KA-72-043

2 x Aluminum landing hear pipe 4 x Plastic rubber ring





2 x Landing gear mount 6 x Cup head socket head screw M3x8mm 6 x Cup head socket head screw M3x14mm

8 x Tail boom mount aluminum gasket 4 x Doubled-headed screw rod Front drive shaft mount KA-72-046 4 x Cup head socket head screw M3x8mm 1 x Plane bearing 05x010x4mm 1 x Gear bearing mount

Middle drive shaft mount KA-72-047



- 1 x Middle drive shaft mount
- 2 x Cup head socket head screw M3x14mm 2 x Plane bearing 06x013x5mm





3 x Surface bearings Ø8x16x5mm 3 x Rubber ring 3 x Tail drive bearing mount

1 x Back-end universal joint drive shaft 1 x Joint Ø3x12mm







- 1 x Tail gear box 2 x Flange Bearings(imported) 06x015x5mm 2 x Cup head socket head screw M3x10mm 4 x Umbrella head socket head machining screws M2x4mm
- 2 x Surface bearing @10x@19x5mm





- 6 x Umbrella head socket head machining screws M2.5x6mm 6 x Flange bearing M2.5x6x2.6mm 1 x Tall rocker arm mount 2 x Coppter washers 02.6x5x0.5mm 1 x Tall rocker arm 2 x Umbrella head socket head machining screws M2x6mm





- 2 x Grub screw M4x4mm
- 4 x Nylon nuts M3
- 4 x Iron washers @3x8X0.6mm
- 2 x Tail rotor hub



- 4 x Grub screw M2.5x10mm
- 2 x CF rudder control rod 4 x Alumnium sleeve for tail boom
- 4 x Tail boom connector



- 2 x CF rudder control rod
- 4 x Metal head of rudder control rod
- 4 x Ball link Ø5.0





- 2 x Frame connecting bolt 2 x Battery plate connecting bolt 2 x ESC fixing bolt 1x Grub screw M3x12mm 10 x Cup hear socket head screw M3x8mm



1 x Swashplate Anti-rotation bracket 2 x Cup head socket head machining screws M2x6mm

Ball link set KA-72-065



Servo mount metal spacers KA-72-066



- 1 x Linkage rod (56MM) 2 x Linkage rod (38MM) 6 x Ball head buckle  $\phi$  5.0





- 1 x Gear coupleaxle
- 5 x Sink head Phillips machining screws M3x6mm 1 x Cup head socket head half tooth screw M4x25mm
- 1 x Nylon nuts M4



- 2 x Tail boom brace mounting ring
- 2 x Nylon nuts M2 2 x Cup head socket head screw M2x10mm





- 1 x Vertical stabilizer mount 3 x Cup head socket head screw M3x10mm 2 x Conical washers 2 x Cup head socket head screw M3x8mm



1 x Tail boom brace mount

2 x Linkage Ball 8 x Linkage Ball φ 5.0 2 x Linkage Ball φ 5.0

- 3 x Cup head socket head screw M3x10mm



10 x Conical washers





2 x Hexnuts M2 2 x CF tail pitch connecting piece 2 x Umbrella head socket head machining screws M2x6mm 2 x Short linkage ball



2 x Tail shaft locking collers ring





# 40.PARTS LIST 4













































# 41.REGULAR MAINTENANCE

Regular maintenance is required to keep the KDA AGILE 7.2 helicopter in optimal and safe flying condition. The model requires precise configuration of the components and settings to be kept by the owner. Maintain regular maintenance on the model to avoid accidents or loss, and optimum performance.

#### MAINROTOR CHECKLIST

- 1.Main Rotor Housing: when the main rotor housing is worn or faulty, there will be obvious vibration and poor flight control. Check the main rotor, main shaft, and feathering shaft for wear or deformity. Replace parts as necessary to eliminate imbalance.
- 2.O-Rings:The O-Rings will lose their elasticity over time. This will cause excess play on rotor and cause instability. Replace them as needed.
- 3. Main Rotor Holder: When the helicopter dose not fly or reacts sluggishly, even after checking for proper setting of pitch and throttle, check the following items: Plastic parts, Bearings, Ball bearings, Rotor Blades.

  Check for excess play or broken parts, or binding or restricted movement. It is important to check for main rotor balance before each flight. Operating the model when out of balance will cause excessive wear and premature failure of parts, possibly resulting in a dangerous situation.
- 4. Control Arm Assembly: Check regularly for cracked, worn, bent or binding control arms and pushrods. Smooth morement of control arms and linkages is required for stable, vibration free flight.
- 5.Swashplate:Check for excess slop in the main ball where the main shaft rides on, and slop or looseness between the plastic and metal surfaces. Swashplate wear will result in poor stability and lack of control during flight. Replace them as necessary.

#### FUSELAGE/CHASSIS

- 1. Main Shaft Bearing: Normal replacement interval for proper operation is between 60-100 flights. If flying 3D or extreme aerobatics often, inspect the bearing more frequently and shorten the interval as necessary.
- 2.One-way Bearing: One-way bearings have longer lifetimes. Failure is not common. To keep the one-way bearing in good operation, remove it to clean and lubricate after every 50 flights. If the main drive gear is loose, you should replace the one-way bearing.
- 3. Drive Belt: Agile and KDS uses only top quality, stretch-proof belts. It is however, impossible to prevent the belt from stretching or wearing out. Check belt tension regularly, and check for the wear on the teeth. Replace it as necessary.

#### LINKAGE RODS&CONNECTING PARTS

During assembly, take special care to keep the connecting parts in smooth operation, and avoid excess play or binding. Failure to do so will result in poor flight stability. The linkage rods and ends will break and wear due to normal usage, crashing, and poor maintenance and environment. Check for wear and proper operation regularly, replace them as needed.

#### TAIL ROTOR SYSTEM

- 1.Tail Rotor Control Set: Check the tail rotor bearing regularly. If there is excess play or gaps, replace it immediately. Avoid any binding or improper contact on the tail components and bearings as this will cause excess wear and heat, potentially melting or deforming the tail system.
- 2.Tail Unit Assembly: Avoid flying in tall grass or weeds. If grass or weed becomes lodged in the tail rotor unit, it will interfere with the operation, and cause the helicopter to lose control. Always check for foreign objects in the tail and clean them off immediately. Avoid using lubricants on the exposed surfaces of the model as it will attract and collect dirt and debris, and cause failure.
- 3. Tail Rotor Housing: Disassemble tail totor housing for cleaning and maintenance after every 50 flights. If the tail does not operate smoothly or shows any signs of stress or wear, please replace immediately.
- 4.Tail Rotor: Check the tail rotor blades regularly for damage, especitlly if the helicopter ever strikes the ground while flying, or after hard landings. Damaged tail rotor blades can induce vibration.







Version No: 20130715