

Version No: 20131025



Thank you for buying Agile products. Please read this manual carefully before assembling. We recommend that you keep this manual for future reference regarding tuning and maintenance.

This radio controlled helicopter is NOT A TOY! It has some technical requirements, you must pay attention to the flying environment and correct operation. Never fly your radio controlled helicopter over people or near crowds. Teenagers must fly under the guardian's guide. Tail Rotor Diameter: Ø260mm Tail Blade Length: 92mm

Motor Pinion: 21T Motor KV: 1100KV

Driving Gear: (21/54)(17/56) Gear Ratio: 21T(8.89:1) Tail Gear Ratio: 3.86:1 Weight(w/o power): 2700g Flying Weight: 3500g

Battery: 22.2V 5000mAh

ESC: 120A

Version No: 20131015

1.INTRODUCTION

Congratulations on your purchase of the Agile 5.5 radio controlled helicopter kit. Agile 5.5 was designed in Europe by Eng. Gaziano Roberto and is proudly manufactured by KDS Model. Our goal was to offer you something different with a minimum of parts, easy maintenance, and outstanding flying performances. It's time to fly different!...







Enjoy the built and have a great time with you Agile 5.5!

IMPORTANT NOTES

R/C helicopters, including the AGILE 5.5 are not toys. R/C helicopters utilize various high-tech products and technologies to provide superior performance. Improper use of this product can result in serious injury or even death. Please read this manual carefully before using and make sure to be conscious of your own personal safety and the safety of others and your environment when operating all AGILE products. Agile 5.5, KDS Model, their affiliates and authorized distributors are not responsible for personal injuries to the operators and others, and property damages that could occur from the assembly, maintenance or your use/misuse of this product. Always respect the rules provided by your local remote control aircraft organization.

NOTE FOR ASSEMBLY

The following manual provide important instructions to correctly assemble the model. It is structured in a logical way, based on the work done in previous step. If you change the order, it may result in additional or unnecessary steps. So we suggest you to read this user manual very carefully to understand correctly the assembly procedure. Failure to do so may not only downgrade performances but also increase the risk of danger. Apply thread lock as indicated, allow the threadlock to cure before mounting parts. It is recommended to use threadlock on each bolt or screw that are engaged with metal parts.

2.SAFETY NOTES

• LOCATE AN APPROPRIATE LOCATION

R/C helicopters fly at high speed, thus posing a certain degree of potential danger. Choose an appropriate flying site consisting of flat, smooth ground, a clear open field, or a large open room, such as gymnasium or warehouse without obstacles. Do not fly near buildings, high voltage cables, or trees to ensure the safety of yourself, others and your model. Do not play your model in inclement weather, such as rain, wind, snow or darkness.



• OBTAIN THE ASSISTANCE OF AN EXPERIENCED PILOT

Before turning on your model and transmitter, check to make sure no one else is operating on the same frequency. Frequency interference can cause your model, or other models to crash. The guidance provided by an experienced pilot will be invaluable for the assembly, tuning, trimming, and actual first flight(recommend you to practice with computer-based flight simulator).



• ALWAYS BE AWARE OF THE ROTATING BLADES

During the operation of the helicopter, the main rotor will be spinning at a high rate of speed. The blades are capable of inflicting serious bodily injury and damage the environment. Be conscious of your actions, and careful to keep your face, eyes, hands, and loose clothing away from the blades. Always fly the model a safe distance from yourself and others, as well as surrounding objects. Never take your eyes off the model or leave it unattended while it is turned on. Immediately turn off the model and transmitter when you have landed the model.





PREVENT MOISTURE

R/C models are composed of many precision electrical components. It is critical to keep the model and associated equipment away from moisture and other contaminants. The introduction or exposure to water or moisture in any form can cause the model to malfunction resulting in loss of use, or a crash. Do not operate or expose to rain or moisture.



• KEEP AWAY FROM HEAT

R/C models are made up of various forms of plastic. Plastic is very susceptible to damage or deformation due to extreme heat and cold climate. Make sure not to store the model near any source of heat such as an oven, or heater. It is best to store the model indoors, in a climate-controlled, room temperature environment.



PROPER OPERATION

Please use the replacement of parts on the manual to ensure the safety of instructors. This product is for R/C model, so do not use for other purpose.



SAFE OPERATION

Operate this unit within your ability. Do not fly under tired condition or improper operation, which may cause danger.



3. Safety Check Before Flying

Before flying, for safety reasons, make sure that no one else is operating a R/C model on the same frequency as yours. Before flying, please check that the power of your transmitter and your helicopter are sufficient for the flight.

Before turning on the transmitter, please check that the throttle stick is in its lowest position, IDLE UP switch must be on OFF position.

When turning off the model, please follow the power on/off procedure. Power ON: turn on the transmitter first, then turn on helicopter power. Power OFF: turn off the helicopter power first and then turn off the transmitter. Improper operating procedure may cause the model to be out of control, so please do make this your habit.

Before operation, check that every movement is smooth and directions are correct. Inspect servos carefully for interferences and broken gears.

Check for missing or loose screws and nuts. See if there is any cracked and/or incomplete assembly of parts.

Check main rotor blades and rotor holders carefully. Broken and premature failures of parts might result in a dangerous situation or crash.

Check all ball links to avoid excess play and replace as needed. Failure to do so will result in poor flight stability.

Check that the battery and power plugs are fastened. Vibrations and violent flight might loosen the plugs and so lead to out of control.

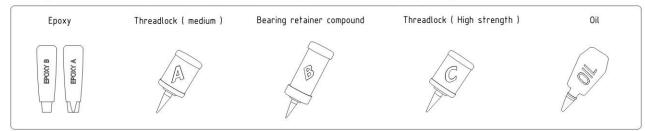
Check for the tension of main drive belt.

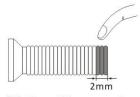
4.Tools Required

- -Hex drivers: 1.5, 2, 2.5, 3, 4mm
- -Nut Drivers: 2, 4, 7mm
- -Ball link pliers
- -Diagonal cutting pliers
- -Scissors
- -Metric ruler
- -Soldering iron + solder (for motor and ESC wiring)
- -Pitch gauge (for set up)
- -Swashplate leveller
- -Threadlock blue * (medium)
- -Threadlock red * (high strength)
- -Bearing retainer compound
- -Epoxy A+B Glue
- -Grease
- -Oil
- *Colors may vary depending on your area.



When you see the marks as below, please use glue or grease to ensure flying safety.





"A" Glue width: approx. 2mm

"OIL" Lubrication grease. "A" thread lock, apply a small amount on screws or metal parts and wipe surplus off. When disassembling, recommend to heat the metal joint about 15 seconds. (NOTE: Keep plastic parts away from heat.)

5. Equipment Required for Assembly

RADIO TRANSMITTER AND ELECTRONIC EQUIPMENT REQUIRED FOR ASSEMBLY

• Brushless electric motor: 6s Lipo - 1100KV / 1700W

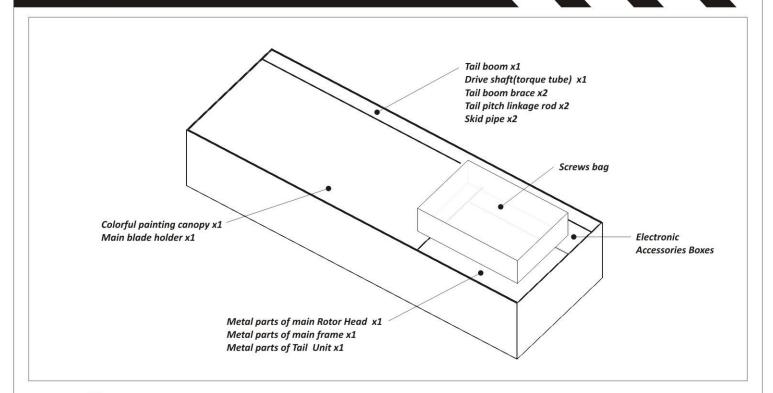
(4mm Bolt holes, 30mm mount width, 6mm * 37mm motor shaft)

•Speed controller: minimum 120A

(ESC specs limits should be rated accordingly to the maximum amps handling by the motor)

- •Lipo Batteries: 6s 4000-5500 mAh
- Electronic flybarless system
- •3 cyclic servos, standard size
- •1 tail rotor servo, standard size, high speed required
- •590 mm main rotor blades
- •95 mm tail rotor blades (included)
- •6 channel or more helicopter transmitter system, 2.4 Ghz frequency preferred
- Receiver 6 channel or more (working with your transmitter specs)

6.Package Illustration

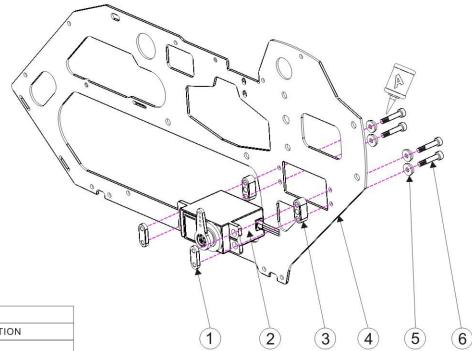




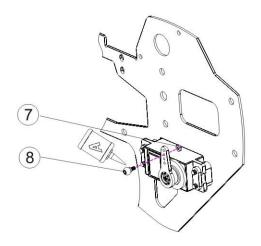
7. Assembly Process of Main Frames and Power System

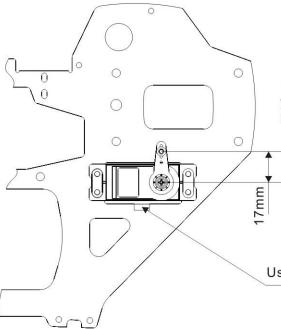
REM:Apply Medium Thread lock or Equivalent to all screws. balls, and threasd which are engaged with metal-parts





		PARTS	SLIST
ITEM	QTY	PART NUMBER	DESCRIP TION
1	2	KA-72-066	Servo Clamp
2	1		Tail Servo
3	2	KA-72-066	Servo Spacer
4	1	KA-55-033	Right Main Frame
5	4	KA-72-074	Frame Aluminum washer
6	4	KA-72-066	Screw M3X16
7	1	KA-55-066	Screw ball nut M2
8	1	KA-55-077	Rudder servo ball



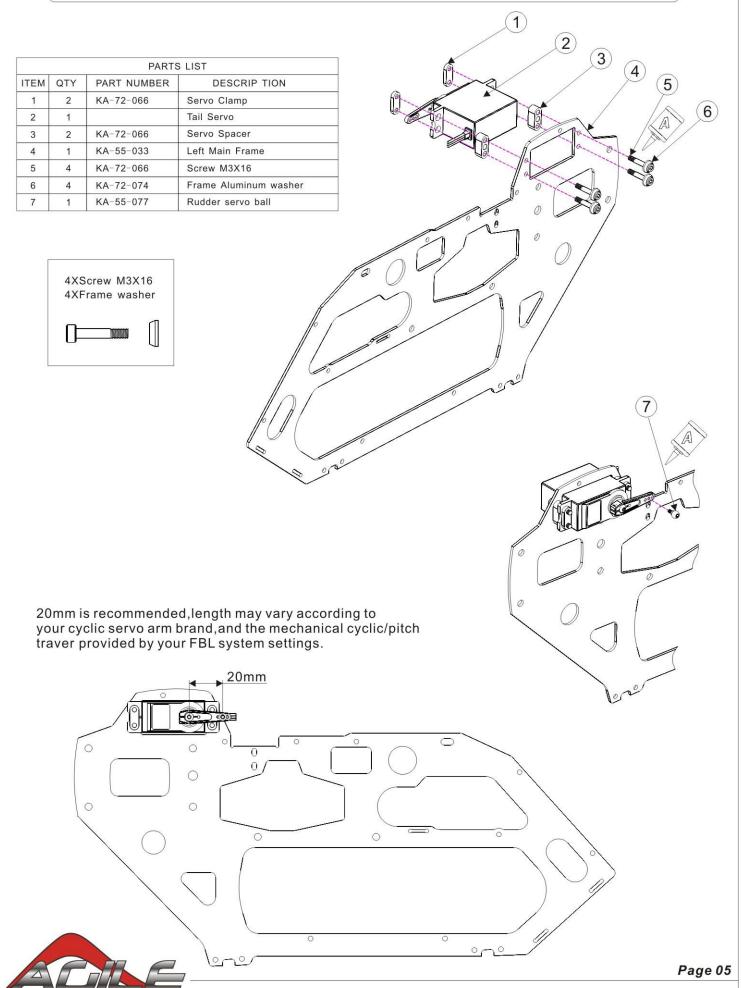


17mm is recommended, but may vary according to your rudder servo arm brand and the mechanical tail traver provided by the tail gyro function of your FBL system.

Use this opening to get your rudder servo wire inside frame



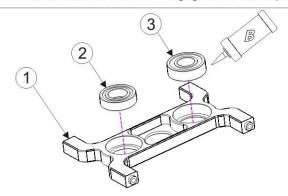
8. Assembly Process of Main Frames and Power System



9.Assembly Process of Main Frames and Power System

REM:Apply Medium Thread lock or Equivalent to all screws. balls, and threasd which are engaged with metal-parts

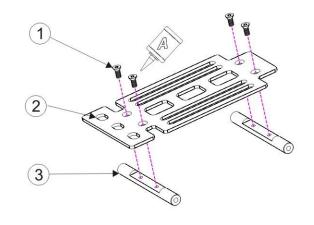
		PARTS	SLIST
ITEM	QTY	PART NUMBER	DESCRIP TION
1	1	KA-55-011	Main shaft bearing
2	1	KA-55-011	Bearing \$10X19X5
3	1	KA-55-011	Bearing ϕ 9X20X6



4XFlat head screw M2.5X6



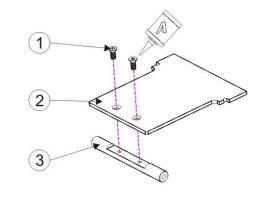
		PARTS	S LIST
ITEM	QTY	PART NUMBER	DESCRIP TION
1	4	KA-55-077	Flat head screw M2.5X6
2	1	KA-55-035	ESC Frame
3	2	KA-55-060	Spacer



2XFlat head screw M2.5X6



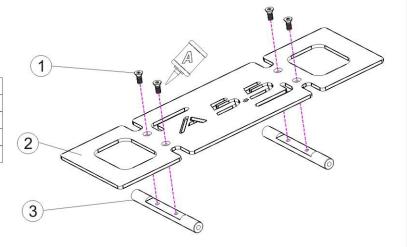
		PARTS	SLIST
ITEM	QTY	PART NUMBER	DESCRIP TION
1	2	KA-55-077	Flat head screw M2.5X6
2	1	KA-55-035	Gyro mount
3	1	KA-55-060	Spacer



4XFlat head screw M2.5X6



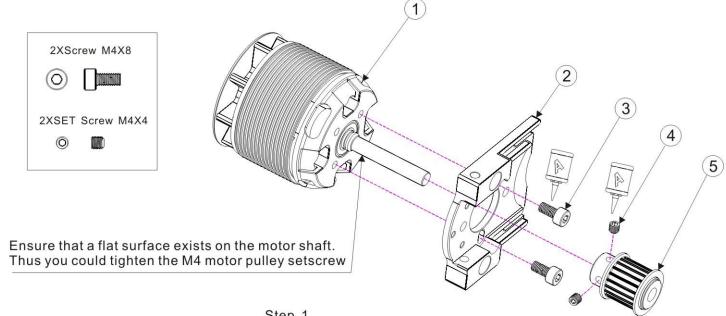
		PARTS	SLIST
ITEM	QTY	PART NUMBER	DESCRIP TION
1	4	KA-55-077	Flat head screw M2.5X6
2	1	KA-55-037	Bottom board
3	2	KA-55-060	Spacer

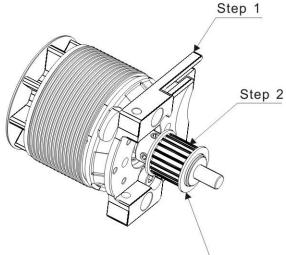




10.Assembly Process of Main Frames and Power System

REM:Apply Medium Thread lock or Equivalent to all screws. balls, and threasd which are engaged with metal-parts

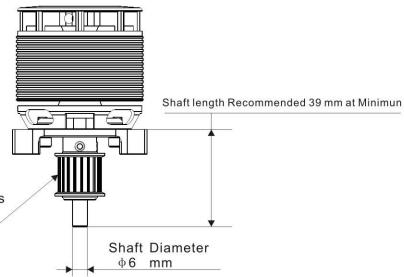




		PARTS	SLIST
ITEM	QTY	PART NUMBER	DESCRIP TION
1	1	BL4020-1100KV	Motor KV: 1100-1200
2	1	KA-72-018	Motor mount
3	2	KA-55-011	Screw M4X8
4	2	KA-55-024	SET Screw M4X4
5	1	KA-55-024	Motro pulley Z=21

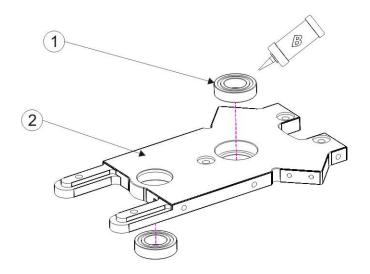
Line up the set screw motor pulley with the motor shaft flat surface.

The motor pulley must be aligned to the pulley by adjusting the height with the main gear of the first stage. so that the belt will stay perfectly horizontal, thus works as well as can be expected

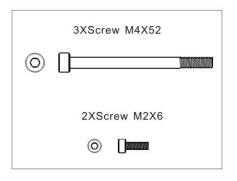


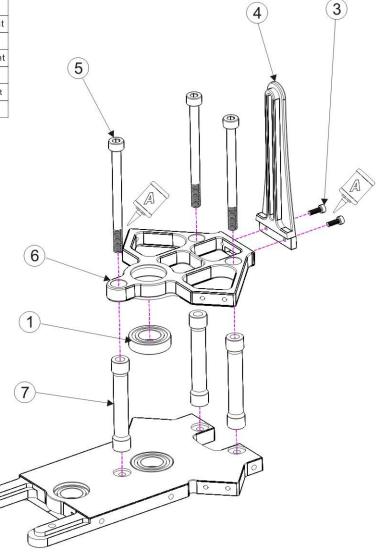


11. Assembly Process of Main Frames and Power System



		PARTS	SLIST
ITEM	QTY	PART NUMBER	DESCRIP TION
1	3	KA-72-088	Bearing ϕ 10X19X5
2	1	KA-55-010	Main shaft middle bearing mount
3	2	KA-72-061	Screw M2X6
4	1	KA-55-033	Swashplate Anti-rotation bracket
5	3	KA-55-012	Screw M4X52
6	1	KA-55-009	Main shaft upper bearing block mount
7	3	KA-55-012	Main shaft bearing block pillar

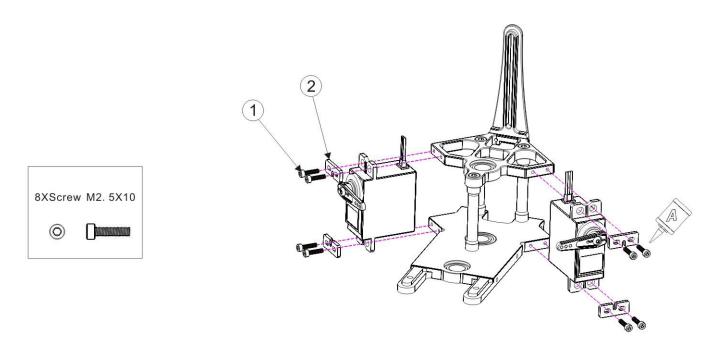




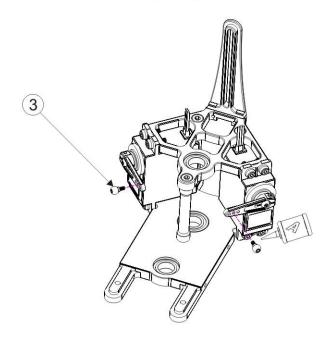


12. Assembly Process of Main Frames and Power System

REM:Apply Medium Thread lock or Equivalent to all screws. balls, and threasd which are engaged with metal-parts

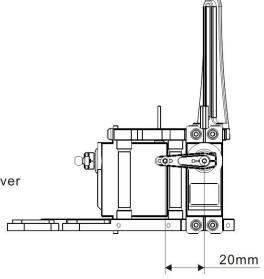


REM:Before mounting servo arms, do not forget to set their neutral position Check the manual of your flybarless system for more informations

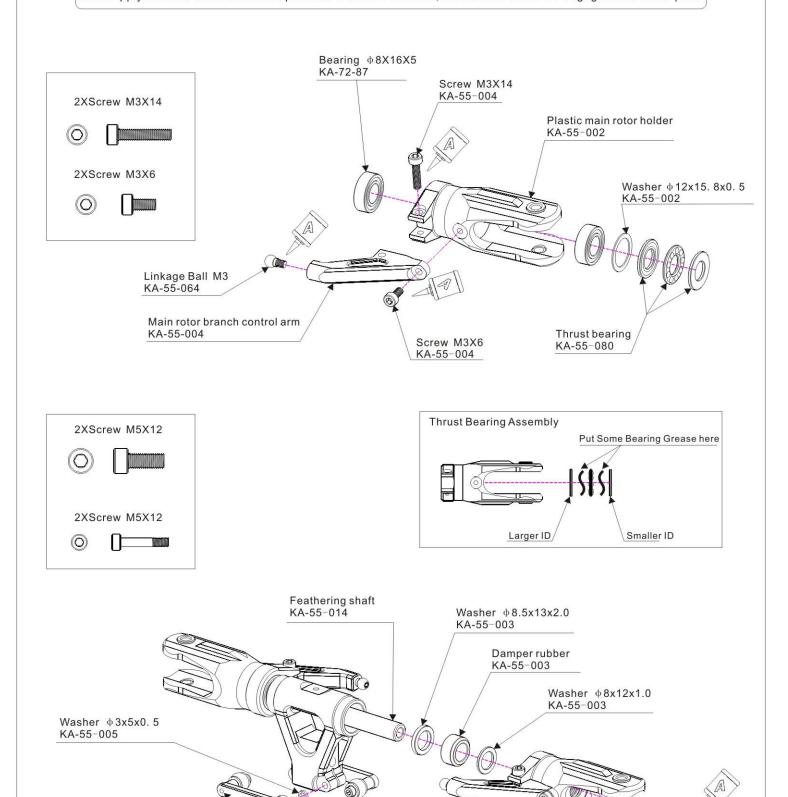


		PARTS	SLIST	
ITEM	QTY	PART NUMBER	DESCRIP TION	
1	8	KA-55-009	Screw M2.5X10	
2	4		Servo Plate	
3	2	KA-55-064	Ball link M2	

20mm is recommended, but may vary according to your rudder servo arm brand and the mechanical tail traver provided by the tail gyro function of your FBL system.







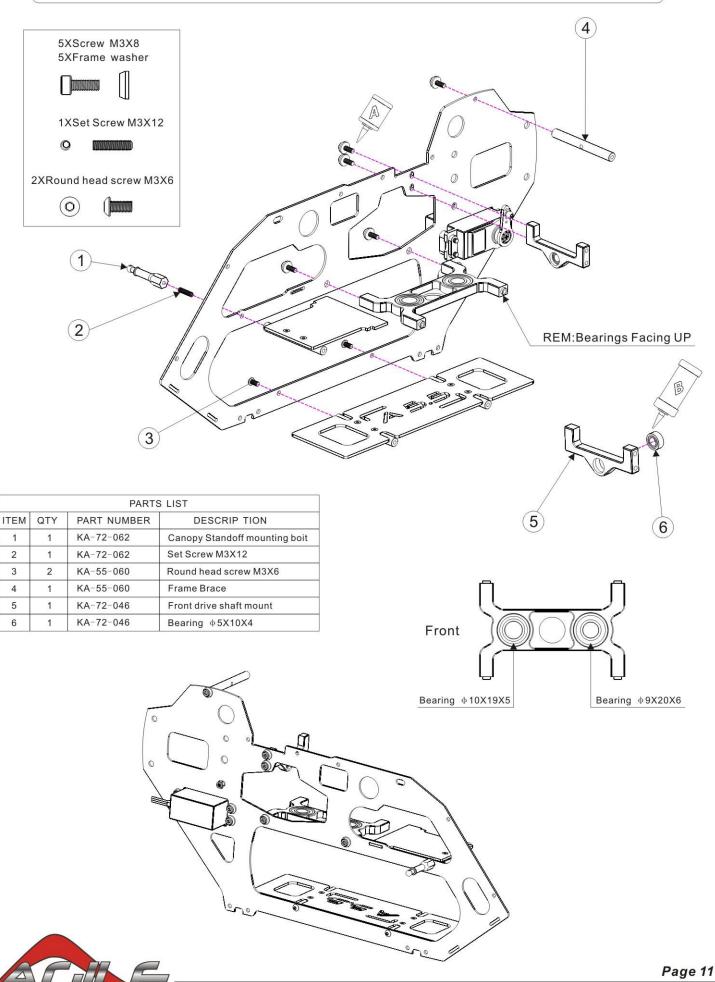
KA-55-005

Screw M3X16 KA-55-005

Screw M5X12 KA-55-014

Washer ϕ 5x13x1.2

KA-55-014



15. Assembly Process of Main Frames and Power System

REM:Apply Medium Thread lock or Equivalent to all screws. balls, and threasd which are engaged with metal-parts

1XNylstop nut M4





1XScrew M4X25

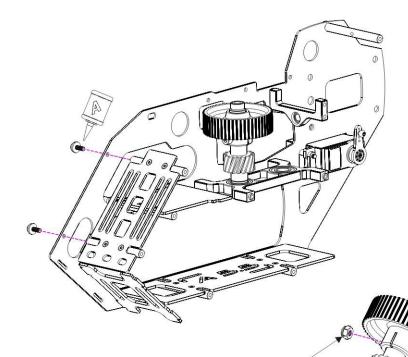




2XScrew M3X8 2XFrame washer







		PARTS	SLIST
ITEM	QTY	PART NUMBER	DESCRIP TION
1	1	KA-55-027	Nylstop nut M4
2	1	KA-55-027	Second reduction gear
3	1	KA-55-026	First reduction gear 54T
4	1	KA-55-027	Screw M4X25
5	1	KA-72-046	Set Screw M3X12
6	1	KA-72-046	Canopy Standoff

7XScrew M3X8 7XFrame washer





2XRound head screw M3X6

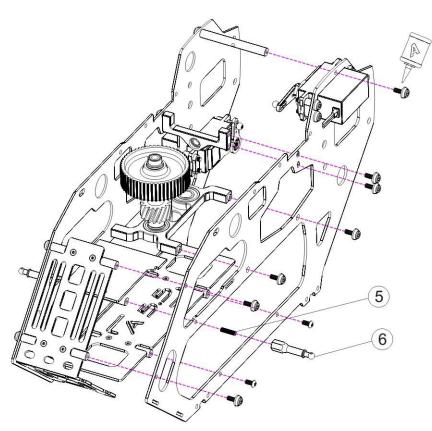




1XSet Screw M3X12







2



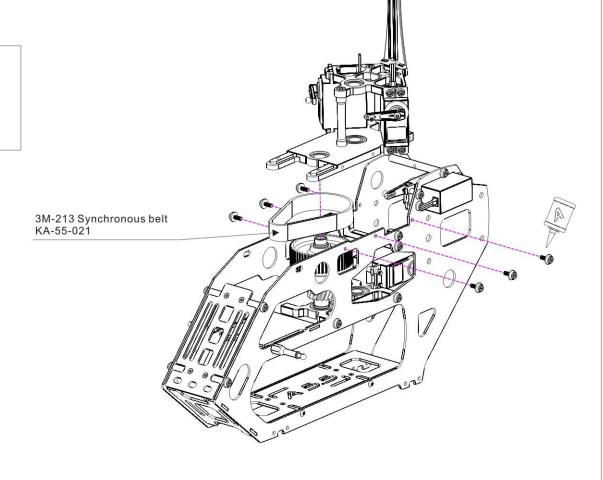
16.Assembly Process of Main Frames and Power System

REM:Apply Medium Thread lock or Equivalent to all screws. balls, and threasd which are engaged with metal-parts

6XScrew M3X8 6XFrame washer



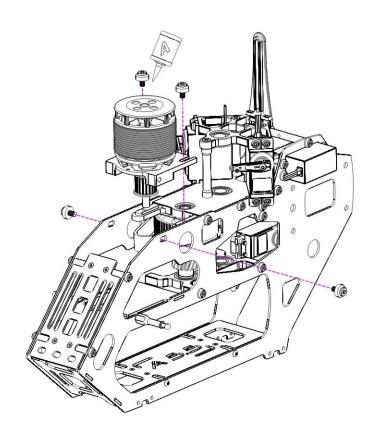




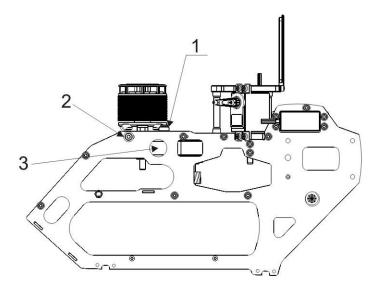
4XScrew M4X10 4XFrame washer







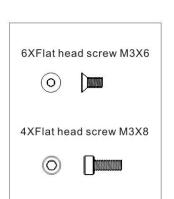


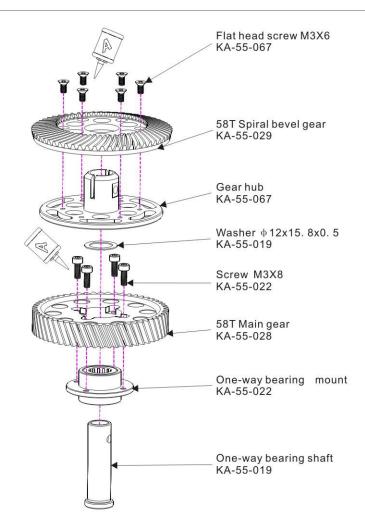


- 1. Push the motor in the opposite direction of the main shaft as far as you can(by hand)
- Z.Tighten slide screws #1
 Tighten motor mount locking screws #2

It should be difficult to push the motor belt.

- 4. Rotate the motor several times by hand. Ensure that belt is correctly aligned with the big pulley
- 5. You can check the belt tension by hand, you just have to push the belt with one of your finger through the round opening on frame #3.







18. Assembly Process of Main Frames and Power System

REM:Apply Medium Thread lock or Equivalent to all screws. balls,and threasd which are engaged with metal-parts

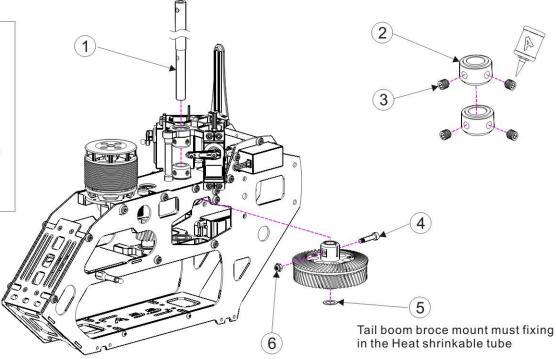


1XNylstop nut M5

1XFlat head screw M4X20

0





		PARTS	SLIST
ITEM	QTY	PART NUMBER	DESCRIP TION
1	1	KA-55-013	Main shaft
2	2	KA-55-016	Lock collar
3	4	KA-55-016	Set Screw M5X5
4	1	KA-55-019	Screw M4X20
5	1	KA-55-076	Washer Φ9.2x13. 8x0. 5
6	1	KA-55-019	Nylstop nut M4
7	4	KA-55-044	Round head screw M3X6
8	4	KA-72-074	Landing skid
9	6	KA-72-066	Screw M3X10
10	4	KA-55-066	Set Screw M3X3
11	2	KA-55-043	Skid pipe

4XRound head screw M3X6





6XFlat head screw M3X10

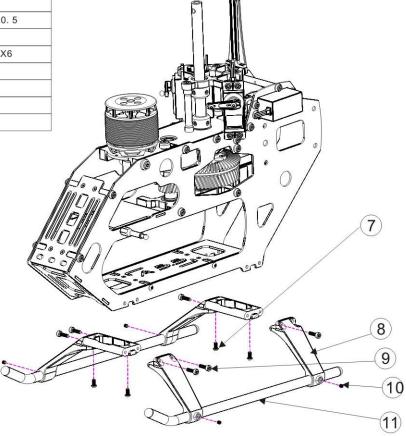




4XSet Screw M3X3

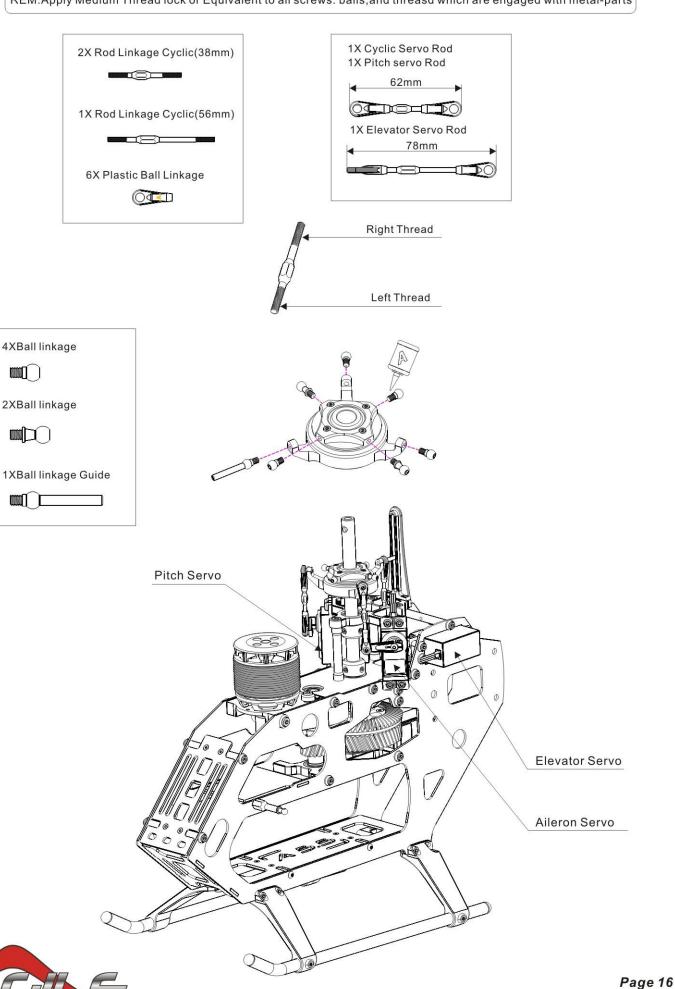


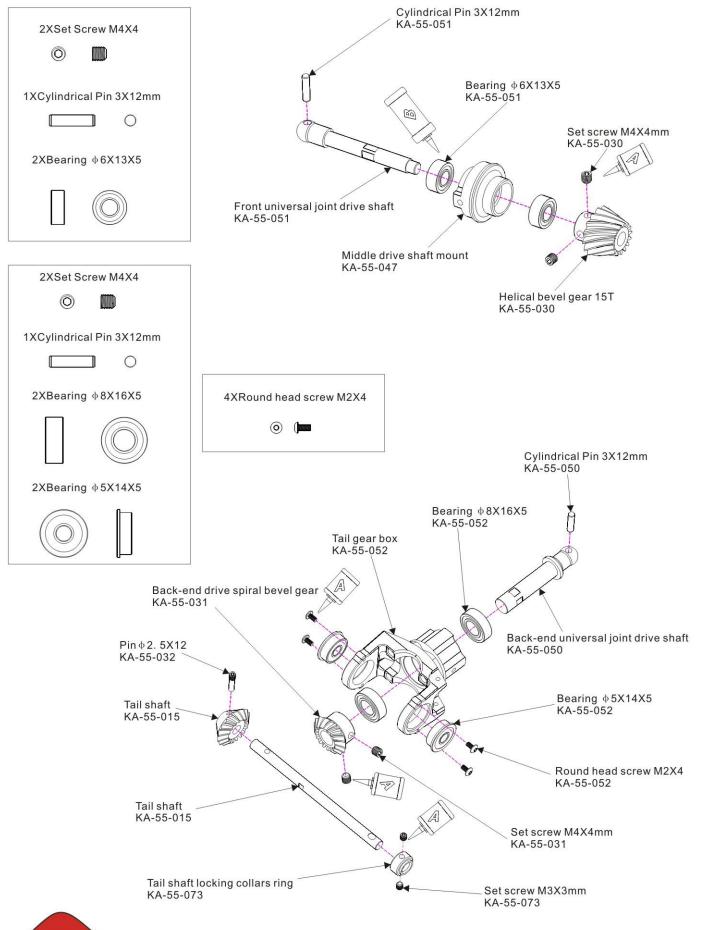


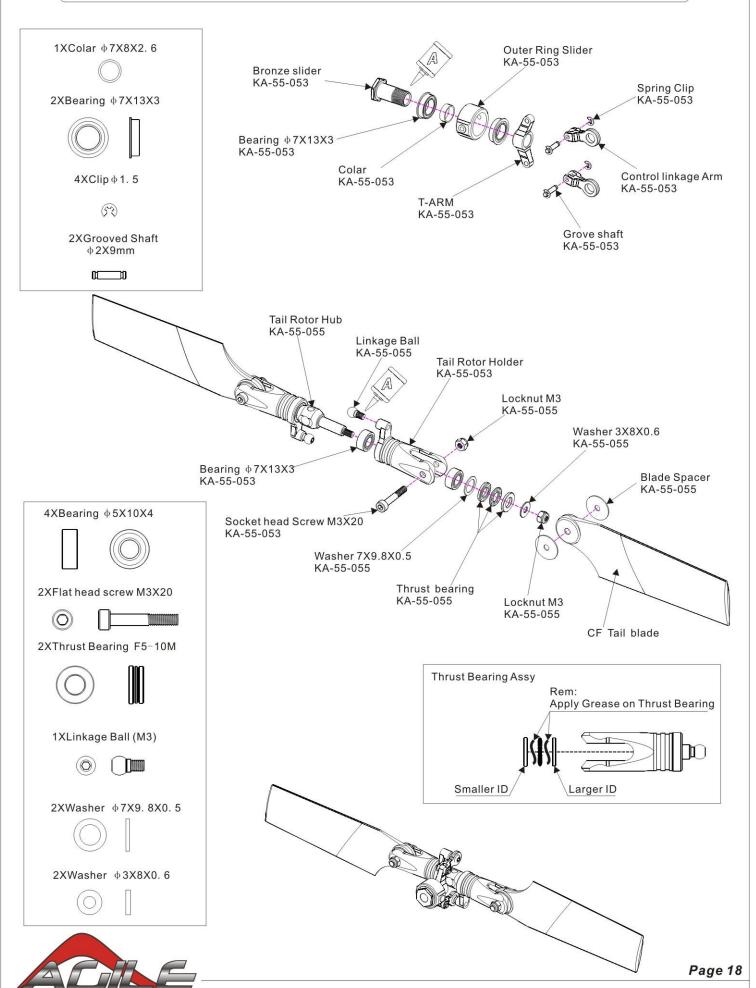




19. Assembly Process of Main Frames and Power System







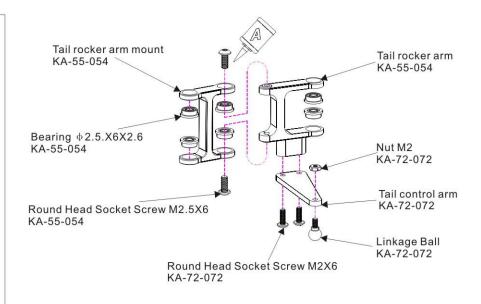
2XRound head screw M2.5X6

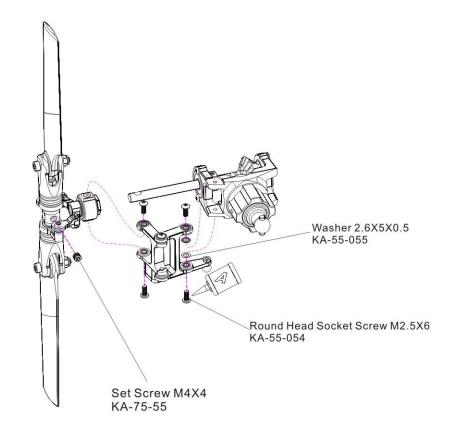
2XRound head screw M2X6

0 (1)

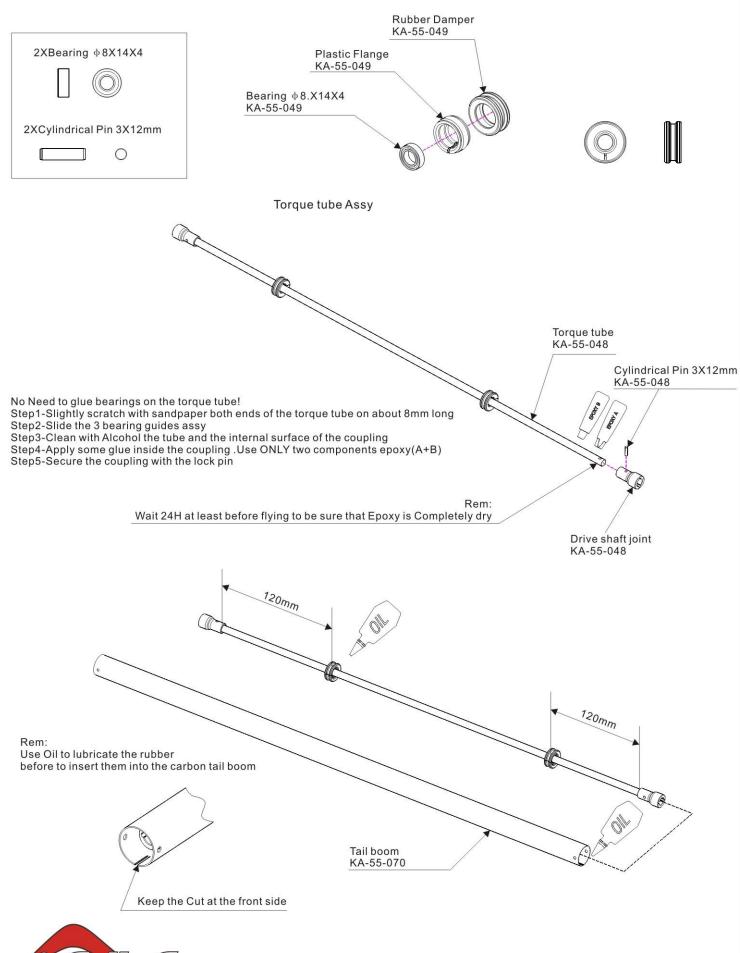
1XLinkage Ball (M2)

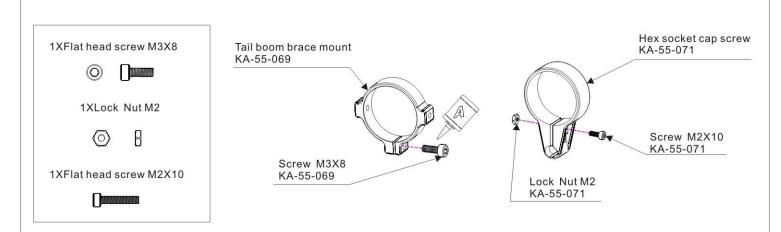
1XNut M2

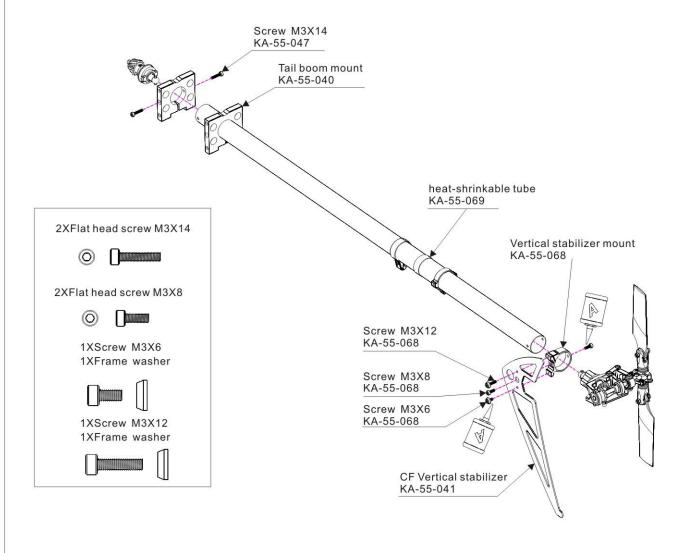












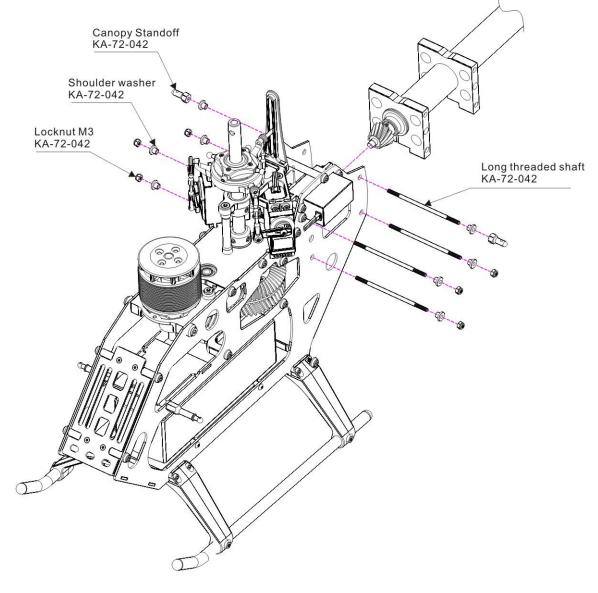


6XLocknut M3

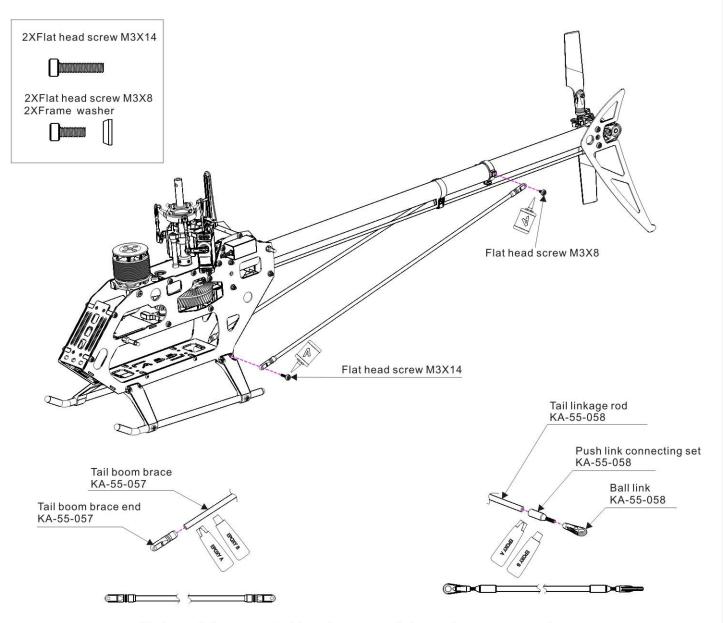
2xCanopy Standoff

8XShoulder washer

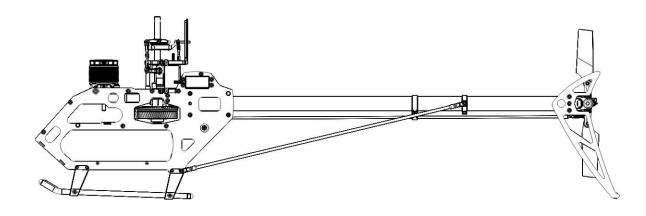
4XLong threaded shaft M3X72



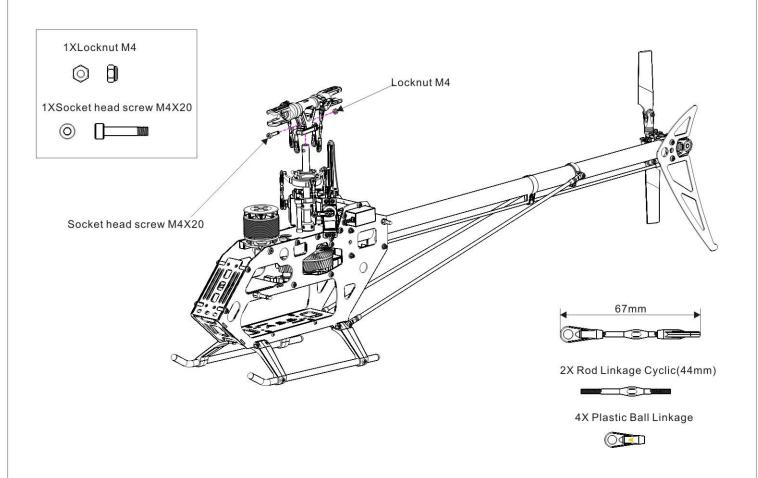


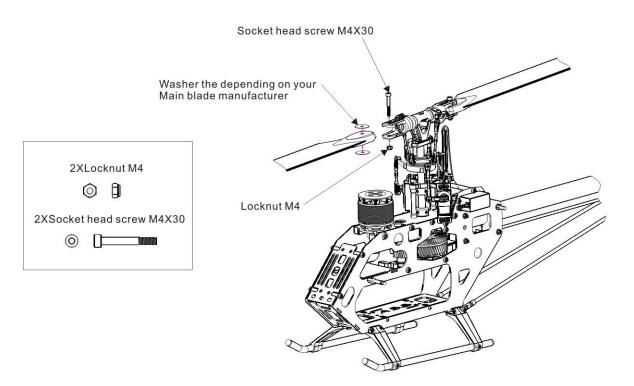


The best solution to mount tail boom brace correctly is to apply some epoxy as shown. Then, screw them on position of Agile main frames and tail boom clamp. Insert set screws to secure. And let Epoxy drying for at least 24H.





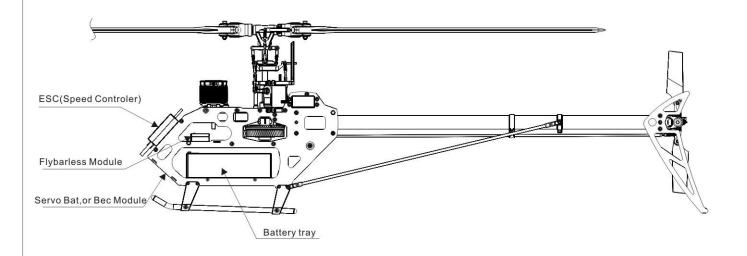


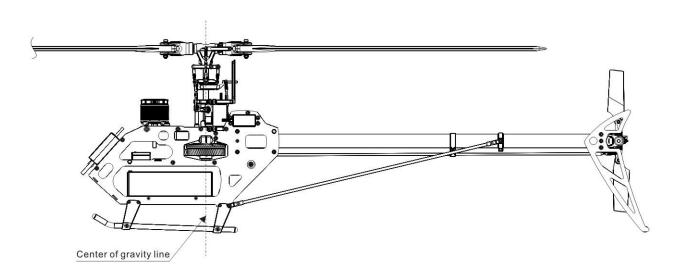




29.Examples of positioning the Electronic Components

REM:Apply Medium Thread lock or Equivalent to all screws. balls, and threasd which are engaged with metal-parts





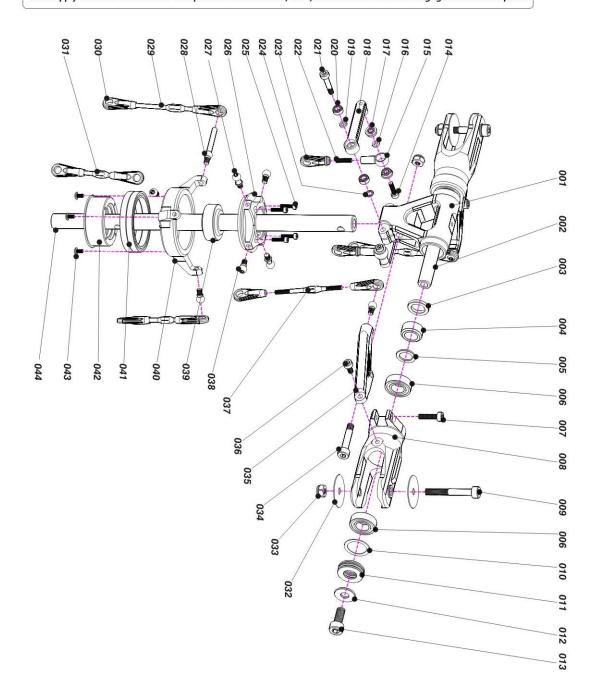
- 1)Check the servo direction, according to your flybarless module.
- 2) make sure your helicopter is well balanced in term of center of gravity passing thrue the main shaft

Calculation for your total ratio:

Pigeon Z=20 (54/20)X(56/17)=8.89

Pigeon Z=21 (54/21)X(56/17)=8.46

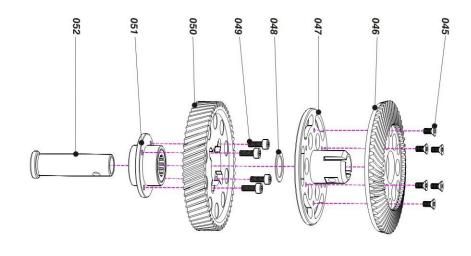




7	Main shaft	KA-55-013	044
7	Button head socket cap (M2*4)	KA-55-007	043
1	Inner lower	KA-55-007	042
2	Bearing (\$ 30* \$ 37*4)	KA-55-007	041
1	Swashplate Outer ring	KA-55-007	040
1	Oscillating bearing	KA-55-007	039
2	Slinkage ball B	KA-55-007	038
2	Linkage rod (44mm)	KA-55-063	037
2	Hex socket cap screw (M3+6)	KA-55-004	036
2	Main rotor branch control arm	KA-55-004	035
2	Hex socket cap screw (M4*20)	KA-55-003	034
5	M4 NUT	KA-55-002	033
4	Washer (KA-55-002	032
2	Linkage rod (38mm)	KA-55-063	031
12	Ball link B	KA-55-063	030
1	Linkage rod (56mm)	KA-55-063	029
1	Swashplate mounting pin	KA-55-007	028
1	Slinkage ball A linkage	KA-55-007	027
6	Swashplate Inner upper part	KA-55-007	026
4	Hex socket cap screw (M2*8)	KA-55-005	025
2	Washer (♦ 3* ♦ 5*0.5)	KA-55-005	024
2	Linkage ball A	KA-55-005	023
2	KIMI screw (M2.5*10)	KA-55-005	022
10	Hex socket cap screw (M3*16)	KA-55-005	021
4	Bearing (+ 3* + 6*2.5)	KA-55-005	020
2	Washer (♦ 3* ♦ 4.5*1.1)	KA-55-005	019
2	Flybarless swashplate control arm	KA-55-005	018
4	Bearing (\$ 2.5* \$ 6*2.6)	KA-55-005	017
2	Washer (♦ 25* ♦ 4.5*1.1)	KA-55-005	016
2	Flybarless linkage arm	KA-55-005	015
2	Hex socket cap screw (M2.5*12)	KA-55-005	014
2	Hex socket cap screw (M5*12)	KA-55-014	013
2	Washer (♦ 5* ♦ 13*1.2)	KA-55-014	012
2	Thrust bearing (F8-16M)	KA-55-002	011
2	Washer (\phi 12* \phi 15.8*0.5)	KA-55-002	010
2	Hex socket cap screw (M4×30)	KA-55-002	009
2	Plastic main rotor holder	KA-55-002	800
6	Hex socket cap screw (M3*14)	KA-55-004	007
6	Bearing (\$\phi 8* \$\phi 16*5)	KA-55-002	900
2	Washer (KA-55-003	005
2	Damper rubber (\$ 7.9* \$ 13*6.5)	KA-55-003	004
2	Washer (KA-55-003	003
1	Feathering shaft	KA-55-014	002
1	Main rotor housing	K4-55-003	001
Quantity	Description	Part No.	NO.

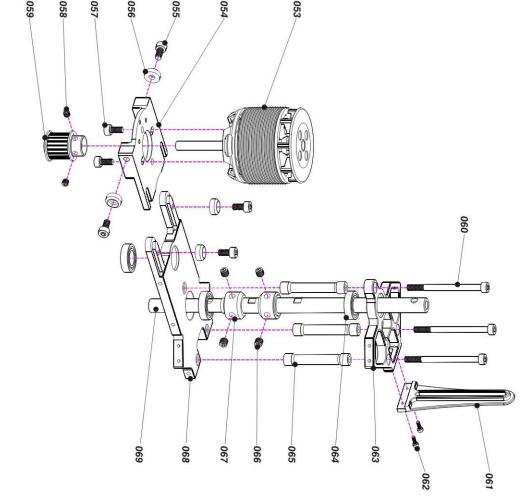


1	One-way simultaneous axis	KA-55-019	052
1	One way clutch mount	KA-55-022	051
1	58T Main gear	KA-55-028	050
1	Hex socket cap screw (M3*8)	KA-55-022	049
1	Washer (\$12.1* \$17*0.5)	KA-55-019	048
1	Gear hub	KA-55-067	047
1	57T Spiral bevel gear	K4-55-029	046
6	Flat socket head cap (M3*6)	KA-55-067	045
Quantity	Description	Part No.	No.

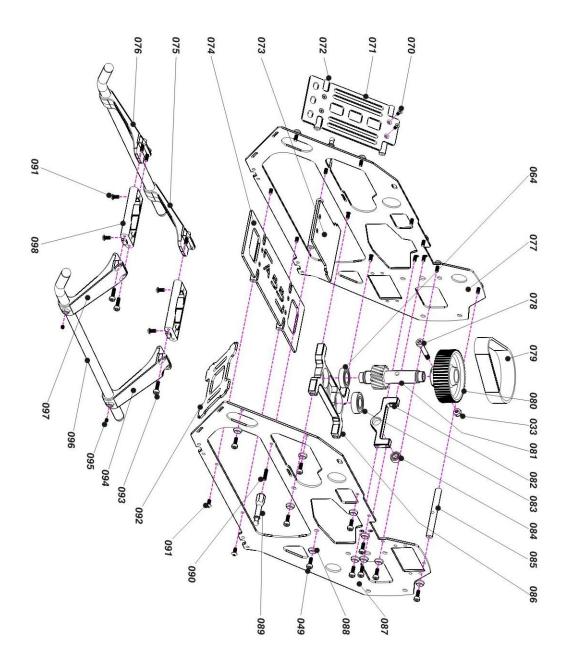


Swashplate Anti-rotation bracket	KA-72-061	061
Hex socket cap screw (M4*52)	KA-55-012	060
21T Main pinion gear	KA-55-024	059
KIMI screw (M4*4)	KA-55-024	058
Hex socket cap screw (M4*8)	KA-72-018	057
Aluminum washer	KA-72-018	056
Hex socket cap screw (M4*10)	KA-72-018	055
Moto mountr	KA-72-018	054
BL4020-1100KV Motor 1100KV	BL4020-1100KV	053

	Main shaft	KA-55-013	069
	Main shaft middle bearing mount	KA-55-010	890
	Lock collar	KA-55-016	067
	KIMI screw (M5*5)	KA-55-016	066
	Main shaft bearing block pillar	KA-55-012	065
	Bearing (\(\phi 10^* \(\phi 19^*5 \)	KA-55-009	064
	Main shaft upper bearing block mount	KA-55-009	063
2	Hex socket cap screw (M2*6)	KA-72-061	062







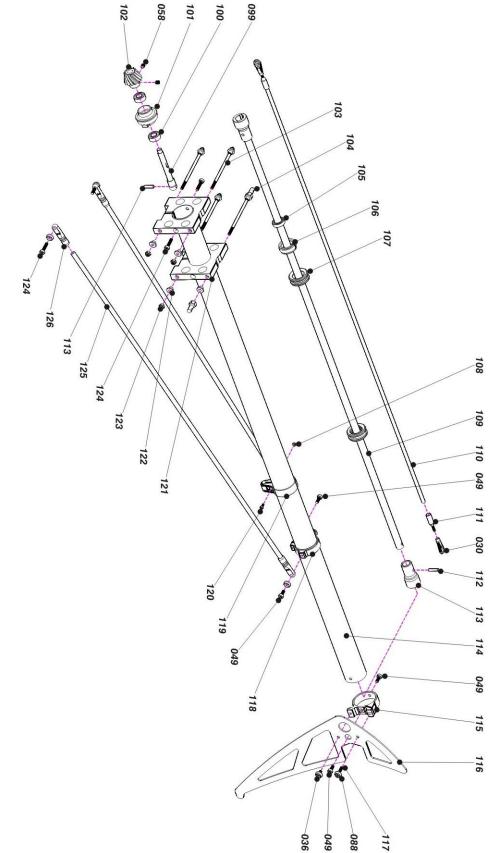
1 1	6	1	6	1	00	2	2	34	1	1	1	51	1	1	1	1	1	1	1	1	1	1	1	5	1	10	Quantity
Skid pipe	KIMI screw (M3*3)	Left rear landing skid,	Hex socket cap screw (M3*10)	CF front electronics board	Button head socket cap (M3*6)	KIMI screw (M3*12)	Front canopy mounting bolt	Conical washers	Main frame L	Main shaft under bearing block(botton plate)	Frame columns(spacers)	Bearing (\$5* \$10*4)	Bearing (4 9* 4 20*6)	Front drive shaft mount	Second reduction gear	First reduction gear 54T	3M-213 Synchronous belt	Hex socket cap screw (M4×25)	Main frame R	Right front landing skid	Right rear landing skid	Bottom plate	CF middle electronic board	Frame connecting bolt	Swashplate	Sink hexangular screw (M2.5*6)	Description
KA-55-043	KA-55-044	KA-55-044	KA-55-044	KA-55-036	KA-55-060	KA-72-062	KA-72-062	KA-55-077	KA-55-034	K4-55-011	KA-55-060	KA-72-046	KA-55-011	KA-72-046	KA-55-027	KA-55-026	KA-55-021	KA-55-026	KA-55-033	KA-55-044	KA-55-044	KA-55-037	KA-55-038	KA-55-060	KA-55-035	KA-55-077	Part No.
096	095	094	093	092	091	090	089	880	087	086	085	084	083	082	081	080	079	078	077	076	075	074	073	072	071	070	No.



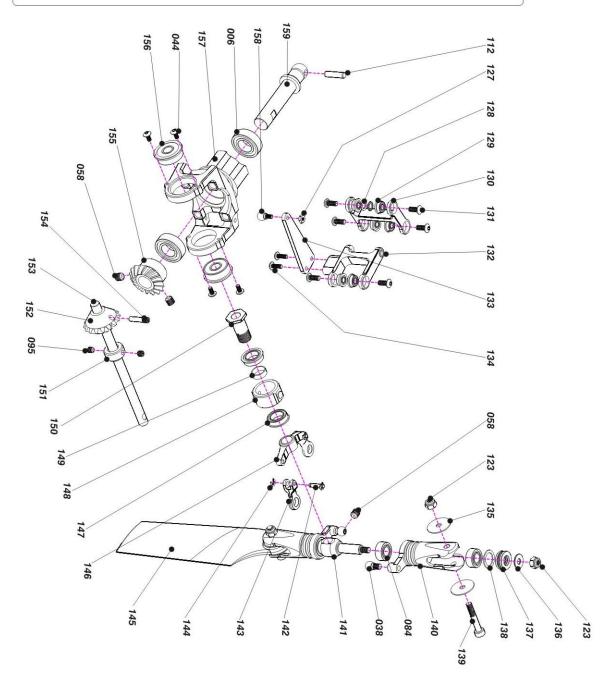
107 KA-55-049	106 KA-55-049	105 KA-55-049	104 KA-72-062	103 KA-72-042	102 KA-55-030	101 KA-55-047	100 KA-55-047	099 KA-55-051	No. Part No.
Rubber damper	Tail drive bearing mount	Bearing (Behind canopy mounting bolt	Doubled-headed screw rod	Helical bevel gear 15Z	Middle drive shaft mount	Bearing (+ 6* + 13*5)	Front universal joint drive shaft	Description
2	2	2	2	4	1	1	2	1	Quantity

117	116	115	114	113	112	111	110	109	108
KA-55-068	KA-55-041	KA-55-068	KA-55-070	KA-55-048	KA-55-048	KA-55-058	KA-55-058	KA-55-048	KA-55-071
Hex socket cap screw (M3*12)	CF vertical stabilizer	Vertical stabilizer mount	Tail boom	Drive shaft joint	Pin (\$3*12)	Push link connecting set	Tail linkage rod	Torque tube	M2 Nut
1	1	1	1	2	4	2	1	1	1

126	125	124	123	122	121	120	119	118
KA-55-057	KA-55-057	KA-55-047	KA-72-062	KA-72-042	KA-55-040	KA-55-071	KA-55-071	KA-55-069
Tail boom brace end	Tail boom brace	Hex socket cap screw (M3*14)	M3 Nut	Aluminum sleeve	Tail boom mount	Hex socket cap screw (M2*10)	Hex socket cap screw	Tail boom brace mount
4	2	4	10	00	2	1	1	1







159	158	157	156	155	154	153	152	151	150	149	148	147	146	145	144	143	142	141	140	139	138	137	136	135	134	133	132	131	130	129	128	127	10000000
KA-72-015	KA-55-050	K4-55-052	KA-55-052	K4-55-031	K4-55-032	KA-55-015	K4-55-032	KA-55-073	K4-55-053	K4-55-053	KA-55-053	K4-55-053	K4-55-053		KA-55-053	KA-55-053	KA-55-053	KA-72-055	KA-72-055	KA-72-055	KA-72-055	KA-72-055	KA-72-055	KA-72-055	KA-72-072	KA-72-072	KA-55-054	KA-55-054	KA-55-054	KA-55-054	KA-72-072	KA-72-072	CONTRACTOR CONTRACTOR
Back-end universal joint drive shaft	Linkage ball C	Tail gear box	Bearing (ϕ 5* ϕ 14*5)	Tail shaft spiral bevel gear 16T	Pin (ϕ 2.5*12)	Tail shaft	Back-end drive spiral bevel gear 15T	Tail shaft locking collers ring	Tail push bearing	Aluminum sleeve (\$7* \$8*2.6)	Tail push bearing mount	Bearing (ϕ 7* ϕ 11*3)	T type arm	CF Tail blade	E-ring	Ball link for tail holder	Pin ($+ 2*9$)	Tail rotor T type holder	Tail rotor holder	Hex socket cap screw (M3*20)	Washer (♦ 7* ♦ 9. 8*0. 5)	Thrust bearing(F5-10M)	Washer (♦ 3* ♦ 8*0.6)	Washer (♦ 3* ♦ 15*0.5)	Round head hex socket screw (M2.5*6)	Tail control arm	Tail rocket arm	Round head hex socket screw (M2.5*6)	Tail rocker arm mount	Bearing ($+2.5*+5*2.6$)	Washer (♦ 2.6* ♦ 5*0.5)	M2 NUT	
1	51	1	2	1	1	1	1	1	1	1	1	2	1	1	4	2	2	1	2	2	2	2	2	4	2	1	1	6	1	6	2	5	Guarany









- 2 x Rotor holder

- 2 x Rotor holder
 4 x Bearing 08x016x5mm
 2 x Washers 012x015.8x0.5mm
 4 x PVC washers 04x020x0.5mm
 2 x Socket head screw M4x30mm
 2 x Lock nut M4
 2 x HF8-16M Thrust bearing



- 1 x Main Rotor Housing
- 1 x Main Rotor Housing 2 x Washers 08x912x1mm 2 x Washers 08.5x913x2mm 2 x Rubber ring (dampers) 07.9x013x6.5mm 1 x Socket head screw M4x20mm 1 x Locking nut M4



- 2 x Rotor holder arm 2 x Socket head screw M3x6mm 2 x Socket head screw M3x14mm



- 4 x Bearing 03x06x2.5mm 4 x Bearing 02.5x06x2.5mm 2 x Double-headed screw 2 x Ball link



Main shaft upper bearing block mount KA-55-009



- 1 x Upper Bearing mount 4 x Socket head screw M2.5x10 1 x Bearing Ø10xØ19x5mm

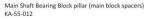


- 1 x Middle Bearing mount
- 4 x Socket head screw M2.5x10 6 x Socket head screw M3x8 2 x Socket head screw M4x10
- 2 x Aluminum space
- 1 x Bearing Ø10xØ19x5mm

Feathering shaft (spindle) KA-55-014



1 x Under Bearing Block 4 x Cup head socket head screw M3x8 2 x Bearing \emptyset 10x \emptyset 19x5mm





3 x Bearing Block pillar 3 x Socket head screw M4X52mm

1 x Swashplate (complete)



2 x Feathering shaft 4 x Washers Ø5xØ13x1.2mm 4 x Cup head socket head screw M5X12mm



Main Shaft spacing ring (locking collers set) KA-55-016



2 x Spacing ring collers 4 x Set screws M5X5mm

2 x Main Shaft Feathering shaft dampers KA-55-017



4 x Dampers



- 1 x Upper motor block 2 x Aluminum spacer 2 x Cup head socket head screw M4x10mm 2 x Cup head socket head screw M4x8mm

Shaft sleeve KA-55-019

- 1 x under motor block
- 1 x imported plane bearing 012x015.8x0.5mm 2 x Cup head socket head screw M4x20mm

Synchronous main motor belt KA-55-021



1 x Synchronous belt GATES-213-3M 14mm



- 1 x Overrunning clutch mount 4 x Socket head screw M3X8 1 x One-way clutch 018x035x16mm



Motor pinion gear 21T KA-55-024 1 x Motor gear 2 x Set screws M4X4mm First reduction gear 45T KA-55-026

1 x Reduction gear 1 x Socket head screw M4X25 1 x Lock nut M4

Second reduction gear KA-55-027

1 x stainless steel gear 1 x Socket head screw M4X25 1 x lock nut M4









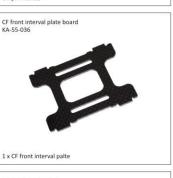






























1 x Plane bearing 05x010x4mm1 x Gear bearing mount

















- 2 x Flange bearing 06x015x5mm 6 x Round head socket head screw M2.5X6mm 2 x Round head socket head screw M2X6mm





- 2 x Grub screw M4x4mm 4 x Nylon nuts M3 4 x Iron washers Ø3x8X0.6mm 2 x Tail rotor hub





- 2 x CF rudder control rod
- 4 x Metal head of rudder control rod 4 x Ball link $\emptyset 6.0$



- 1 x Frame connecting bolt 5 x Battery plate connecting bolt 2 x ESC fixing bolt 2 x Grub screw M3x12mm

- 6 x Cup hear socket head screw M3x8mm



- 1 x Swashplate Anti-rotation bracket
- 2 x Cup head socket head machining screws M2x6mm



2 x cup head socket head screw M3x14mm





- 1 x Linkage rod (56mm)
- 2 x Linkage rod (38mm) 2 x Linkage rod (44mm)

Linkage ball set



- 1 x Cross plate guide post
- 2 x Intermediate linkage ball 05.0 8 x Short ball head 05.0 M3
- 5 x Short ball head 05.0 M2



2 x Linkage Ball 2 x Linkage Ball Ø5.0 12 x Linkage Ball Ø5.0



4 x Cup head socket head half tooth screw M3x16mm

2 x Servo mount metal spacers 2 x Servo cover plate

Gear hub KA-55-067



- 1 x Gear coupleaxle 6 x Sink head Phillips machining screws M3x6mm 1 x Cup head socket head half tooth screw M4x20mm 1 x Nylon nuts M4



- 1 x Vertical stabilizer mount 2 x Socket head screws M3X8mm 1 x Socket head screws M3X6mm 3 x Socket head screws M3X12mm
- 2 x Aluminum spacer



1 x Tail boom brace mount

Tail shaft locking collers ring

- 2 x Conical washers 3 x Cup head socket head screw M3x8mm



1 x CF Tail boom @23.5x@25x675mm

Tail boom brace mounting ring KA-55-071



- 2 x Tail boom brace mounting ring 2 x Nylon nuts M2 2 x Cup head socket head screw M2x10mm



- 2 x Hexnuts M2
- 2 x CF tail pitch connecting piece
 2 x Umbrella head socket head machining screws M2x6mm
 2 x Short linkage ball

1 x Washers set



2 x Tail shaft locking collers ring 4 x Grub screw M3x3mm

1 x Screws set

Conical washers KA-72-074

10 x Conical washers



Battery straps x2

Washers set KA-55-076



1 x Canopy 4 x Canopy rubber ring





2 x Thrust bearings F5-10M



2 x Thrust bearings F8-16M



2 x Flange bearings 02.5x06x2.6mm

Flange bearings KA-72-081



Flange bearings KA-72-083



2 x Flange bearings 05x014x5mm

Surface bearings KA-72-085

2 x Surface bearings 05x010x4mm

Surface bearings KA-72-086

2 x Surface bearings 06x013x6mm





2 x Surface bearings @10x@19x5mm

Surface bearings KA-55-089



2 x Surface bearings 03x06x2.5mm

Surface bearings KA-55-090

2 x Surface bearings @8x@14x4mm



Surface bearings KA-55-092



2 x Surface bearings @9x@20x6mm

Brushless motor BL4020-1100KV 1 x Brushless motor

CF Tail blade KA-55-094

2 x CF Tail blade

CF Main blade 1193-10 2 x CF Main blade

AGILE competition grade 1193-10



1 x AGILE 5000MAH 6S 50C



39.REGULAR MAINTENANCE

Regular maintenance is required to keep the KDS AGILE 5.5 helicopter in optimal and safe flying condition. The model requires precise configuration of the components and settings to be kept by the owner. Maintain regular maintenance on the model to avoid accidents or loss, and optimum performance.

MAINROTOR CHECKLIST

- 1.Main Rotor Housing: when the main rotor housing is worn or faulty, there will be obvious vibration and poor flight control. Check the main rotor, main shaft, and feathering shaft for wear or deformity. Replace parts as necessary to eliminate imbalance.
- 2.O-Rings:The O-Rings will lose their elasticity over time. This will cause excess play on rotor and cause instability. Replace them as needed.
- 3. Main Rotor Holder: When the helicopter dose not fly or reacts sluggishly, even after checking for proper setting of pitch and throttle, check the following items: Plastic parts, Bearings, Ball bearings, Rotor Blades.

 Check for excess play or broken parts, or binding or restricted movement. It is important to check for main rotor balance before each flight. Operating the model when out of balance will cause excessive wear and premature failure of parts, possibly resulting in a dangerous situation.
- 4. Control Arm Assembly: Check regularly for cracked, worn, bent or binding control arms and pushrods. Smooth morement of control arms and linkages is required for stable, vibration free flight.
- 5.Swashplate:Check for excess slop in the main ball where the main shaft rides on, and slop or looseness between the plastic and metal surfaces. Swashplate wear will result in poor stability and lack of control during flight. Replace them as necessary.

FUSELAGE/CHASSIS

- 1. Main Shaft Bearing: Normal replacement interval for proper operation is between 60-100 flights. If flying 3D or extreme aerobatics often, inspect the bearing more frequently and shorten the interval as necessary.
- 2.One-way Bearing: One-way bearings have longer lifetimes. Failure is not common. To keep the one-way bearing in good operation, remove it to clean and lubricate after every 50 flights. If the main drive gear is loose, you should replace the one-way bearing.
- 3. Drive Belt: Agile and KDS uses only top quality, stretch-proof belts. It is however, impossible to prevent the belt from stretching or wearing out. Check belt tension regularly, and check for the wear on the teeth. Replace it as necessary.

LINKAGE RODS&CONNECTING PARTS

During assembly, take special care to keep the connecting parts in smooth operation, and avoid excess play or binding. Failure to do so will result in poor flight stability. The linkage rods and ends will break and wear due to normal usage, crashing, and poor maintenance and environment. Check for wear and proper operation regularly, replace them as needed.

TAIL ROTOR SYSTEM

- 1.Tail Rotor Control Set: Check the tail rotor bearing regularly. If there is excess play or gaps, replace it immediately. Avoid any binding or improper contact on the tail components and bearings as this will cause excess wear and heat, potentially melting or deforming the tail system.
- 2.Tail Unit Assembly: Avoid flying in tall grass or weeds. If grass or weed becomes lodged in the tail rotor unit, it will interfere with the operation, and cause the helicopter to lose control. Always check for foreign objects in the tail and clean them off immediately. Avoid using lubricants on the exposed surfaces of the model as it will attract and collect dirt and debris, and cause failure.
- 3. Tail Rotor Housing: Disassemble tail totor housing for cleaning and maintenance after every 50 flights. If the tail does not operate smoothly or shows any signs of stress or wear, please replace immediately.
- 4.Tail Rotor: Check the tail rotor blades regularly for damage, especitlly if the helicopter ever strikes the ground while flying, or after hard landings. Damaged tail rotor blades can induce vibration.





... it's time to fly different!!!



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